# CRITICAL POINTS OF ARBITRARY ENERGY FOR THE TRUDINGER-MOSER EMBEDDING IN PLANAR DOMAINS 

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#### Abstract

Given a smoothly bounded non-contractible domain $\Omega \subset \mathbb{R}^{2}$, we prove the existence of positive critical points of the Trudinger-Moser embedding for arbitrary Dirichlet energies. This is done via degree theory, sharp compactness estimates and a topological argument relying on the PoincaréHopf theorem. Keywords: Moser-Trudinger, critical inequalities, Leray-Schauder degree, Poincaré-Hopf theorem.


## 1. Introduction

Given a smoothly bounded domain $\Omega \subset \mathbb{R}^{2}$, i.e. a bounded domain with smooth boundary, let $H_{0}^{1}=H_{0}^{1}(\Omega)$ be the usual Sobolev space of functions with zero trace on $\partial \Omega$ endowed with the norm $\|\cdot\|_{H_{0}^{1}}$ given by

$$
\|u\|_{H_{0}^{1}}^{2}=\int_{\Omega}|\nabla u|^{2} d x
$$

Given any positive real number $\beta>0$, our main purpose is to discuss the existence of nonnegative critical points of the classical Moser-Trudinger functional

$$
\begin{equation*}
F(u):=\int_{\Omega}\left(e^{u^{2}}-1\right) d x \tag{1.1}
\end{equation*}
$$

constrained to the submanifold

$$
\begin{equation*}
\mathcal{M}_{\beta}:=\left\{v \in H_{0}^{1}:\|v\|_{H_{0}^{1}}^{2}=\beta\right\} \tag{1.2}
\end{equation*}
$$

of $H_{0}^{1}$. This is equivalent to finding a solution of the following elliptic problem

$$
\left\{\begin{array}{l}
\Delta u=2 \lambda u e^{u^{2}}, u>0 \text { in } \Omega \\
u=0 \text { on } \partial \Omega \\
\int_{\Omega}|\nabla u|^{2} d x=\beta
\end{array}\right.
$$

for some real number $\lambda$, where $\Delta=-\partial_{x x}-\partial_{y y}$ is the (nonnegative) Laplacian.
When $\beta>4 \pi$, this is a long-standing open problem, that can be traced back to the seminal work of Struwe [37], as we shall briefly explain.

Let us first state the celebrated Moser-Trudinger inequality [32, 34, 39] as

$$
\begin{equation*}
\sup _{u \in \mathcal{M}_{\beta}} F(u)<\infty \quad \text { if and only if } \beta \leq 4 \pi \tag{MT}
\end{equation*}
$$

A simple consequence of $(\mathcal{M} \mathcal{T})$ is that for $\beta \in(0,4 \pi)$ the functional $\left.F\right|_{\mathcal{M}_{\beta}}$ admits a maximizer. The existence of maximizers even in the critical case $\beta=4 \pi$, when the Palais-Smale condition does not hold anymore (see [2]), is much more delicate,
and was proven by Carleson-Chang [6] when $\Omega$ is a disk and extended to general bounded domains by Struwe [37] and Flucher [20].

The existence of critical points of $\left.F\right|_{\mathcal{M}_{\beta}}$ in the supercritical regime $\beta>4 \pi$ is even more delicate, due to the critical nature of the nonlinearity which, in addition to the failure of the Palais-Smale condition for every $\beta \geq 4 \pi$ (as shown in [10]), makes the blow-up estimates very subtle and a priori leaves open possibility of no critical points for any $\beta>4 \pi$. Instead, relying on the concentration-compactness principle of Lions and on his own monotonicity trick, still in [37], Struwe proved the existence of $\varepsilon_{0}>0$ such that $\left.F\right|_{\mathcal{M}_{\beta}}$ has a positive local maximizer for every $\beta \in\left(4 \pi, 4 \pi+\varepsilon_{0}\right)$ and a mountain pass-type positive critical point for almost every $\beta \in\left(4 \pi, 4 \pi+\varepsilon_{0}\right)$. The existence of a second positive critical point for every $\beta \in\left(4 \pi, 4 \pi+\varepsilon_{0}\right)$ was proven by Lamm-Robert-Struwe [24] using a flow approach. In these results, there is no condition on the smoothly bounded domain $\Omega$, but on the other hand, the requirement that $\beta$ is close to $4 \pi$ is essential. This, of course, leaves open the question of the existence of critical points of $\left.F\right|_{\mathcal{M}_{\beta}}$ for $\beta$ much larger than $4 \pi$.

That this is not just a technical issue is confirmed by the result of the first and second authors [28], proving that when $\Omega$ is a disk $\left.F\right|_{\mathcal{M}_{\beta}}$ has no positive critical point for $\beta$ sufficiently large. On the other hand, Del Pino-Musso-Ruf [14], in the case in which $\Omega$ is not simply connected and $\beta$ is close to $8 \pi$, or $\Omega$ is an annulus and $\beta$ is close to $4 \pi N$ for some $N \in \mathbb{N}^{\star}:=\mathbb{N} \backslash\{0\}$, used a Lyapunov-Schmidt construction to show the existence of critical points of $\left.F\right|_{\mathcal{M}_{\beta}}$. This suggests that the topology of $\Omega$ plays a crucial role in the solvability of $\operatorname{Problem}\left(\mathcal{E}_{\beta}\right)$, and justifies the assumption of our main result, which reads as follows (see also Remark 2.5 below):

Theorem 1.1. Let $\Omega \subset \mathbb{R}^{2}$ be a smoothly bounded non-contractible domain. Then, given any positive real number $\beta>0$, there exists a nonnegative function $u$, critical point of $F$ constrained to $\mathcal{M}_{\beta} \subset H_{0}^{1}$. In particular, $u$ is smooth and solves $\left(\mathcal{E}_{\beta}\right)$.

Theorem 1.1, complemented with the previous results when $\Omega$ is a disk, gives a fairly complete answer to the problem of the existence of solutions to $\left(\mathcal{E}_{\beta}\right)$.

The case in which the domain $\Omega$ is replaced by a two-dimensional closed surface was recently studied in [12] using the barycenter technique of Djadli-Malchiodi [17] (see also Bahri [3]) taking advantage of the variational structure, a minmax argument together with Struwe's monotonicity trick to obtain solutions of a subcritical approximate problem for almost every $\beta>0$, and blow-up analysis together with energy estimates at critical energy levels to conclude.

In order to prove Theorem 1.1, we will use a different approach, based on the Leray-Schauder degree. This can be divided in 4 main steps. First, assuming that $\beta \notin 4 \pi \mathbb{N}$, we will deformation Problem $\left(\mathcal{E}_{\beta}\right)$ to link it to the Mean-Field equation

$$
\left\{\begin{array}{l}
\Delta u=\beta \frac{2 e^{u}}{\int_{\Omega} e^{u} d x}, \\
u=0 \text { on } \partial \Omega,
\end{array} \quad\left(\mathcal{E}_{\beta}^{M F}\right)\right.
$$

studied e.g. in Ding-Jost-Li-Wang [16], and for which a degree theory approach has been initiated by $\mathrm{Li}[25]$ and developed by Chen and $\operatorname{Lin}[8,9]$.

More precisely, given $\beta>0$, we consider the $p$-dependent family of problems

$$
\left\{\begin{array}{l}
\Delta u=p \lambda u^{p-1} e^{u^{p}}, u>0 \text { in } \Omega, \\
u=0 \text { on } \partial \Omega, \\
\frac{\lambda p^{2}}{2}\left(\int_{\Omega}\left(e^{u^{p}}-1\right) d x\right)^{\frac{2-p}{p}}\left(\int_{\Omega} u^{p} e^{u^{p}} d x\right)^{\frac{2(p-1)}{p}}=\beta,
\end{array}\right.
$$

parametrized by $p \in[1,2]$. Notice that $\left(\mathcal{E}_{2, \beta}\right)$ is equivalent to $\left(\mathcal{E}_{\beta}\right)$ thanks to integration by parts, while $\left(\mathcal{E}_{1, \beta}\right)$ can be easily deformed to $\left(\mathcal{E}_{\beta}^{M F}\right)$.

That these deformations preserve the Leray-Schauder degree is a consequence of the sharp compactness estimates that have been developed in a series of papers ( $[12,18,28,29]$ ), and that we can adapt to the case of a bounded domain (Theorem 2.1), upon ruling out boundary blow-up (thanks to Proposition 2.1 below). In particular for every $N \in \mathbb{N}$ and $\beta \in(4 \pi N, 4 \pi(N+1))$ the Leray-Schauder degree $d_{p, \beta}(\Omega)$ is a constant, not depending on $p \in[1,2]$ and equal to the Leray-Schauder degree $d_{N}^{M F}(\Omega)$ of $\left(\mathcal{E}_{\beta}^{M F}\right)$.

Then is suffices to compute $d_{N}^{M F}(\Omega)$. That $d_{0}^{M F}(\Omega)=1$ is fairly easy, hence the main issue is to compute the degree jumps $d_{N+1}^{M F}(\Omega)-d_{N}^{M F}(\Omega)$ for any $N \in \mathbb{N}$, i.e. (roughly speaking) the number of blowing-up families of solutions $\left(u_{\varepsilon}\right)$ to $\left(\mathcal{E}_{\beta}^{M F}\right)$ with $\beta_{\varepsilon} \rightarrow 4 \pi(N+1)$. Using a Lyapunov-Schmidt construction (a so-called finite dimensional reduction), Chen-Lin [9] reduced this problem to the computation of the Brouwer degree of a finite dimensional vector field, see Proposition 2.3.

The third step is to compute the Brouwer degree of such vector field, i.e. Proposition 2.4. The proof of this proposition, which is the most delicate part of this work and will be given in Section 3, is based on a new topological argument and a blow-up analysis, which allow us to use the Poincaré-Hopf theorem even in the context of bounded domains, when the vector field does not always point outwards. We will state this result in more generality than needed here, because its relevance goes beyond its application to Theorem 1.1. Moreover with minor changes, this result can also be carried and applied to higher even dimension (see comments after Proposition 2.3, and Remark 2.2).

These 3 steps are sufficient to compute the Leray-Schauder degree of $\left(\mathcal{E}_{\beta}^{M F}\right)$, hence of $\left(\mathcal{E}_{p, \beta}\right)$ and $\left(\mathcal{E}_{\beta}\right)$, for every positive $\beta \notin 4 \pi \mathbb{N}$. Finally, in order to also include the case $\beta \in 4 \pi \mathbb{N}^{\star}$, we prove that for $p \in(1,2]$ solutions to ( $\mathcal{E}_{p, \beta}$ ) are compact from the left (Theorem 2.3 below).

Collecting these results we finally obtain:
Theorem 1.2. Let $\Omega \subset \mathbb{R}^{2}$ be a smoothly bounded domain. Let $p \in(1,2], N \in \mathbb{N}$ and $\beta \in\left(4 \pi N, 4 \pi(N+1)\right.$ ] be given. Then the total Leray-Schauder degree $d_{p, \beta}(\Omega)$ of the solutions of $\left(\mathcal{E}_{p, \beta}\right)$ is well-defined and equals the binomial number $\binom{N-\chi(\Omega)}{N}$, where $\chi(\Omega)$ stands for the Euler characteristic of $\Omega$. In particular, if either $\Omega$ is not simply connected or if $N=0$, we have $d_{p, \beta}(\Omega) \neq 0$, so that the set $\mathcal{C}_{p, \beta}(\Omega)$ of the solutions of $\left(\mathcal{E}_{p, \beta}\right)$ is not empty.

We adopt here the usual convention that $\binom{-1}{0}=1$ and $\binom{N-1}{N}=0$ for $N \in \mathbb{N}^{\star}$. We recall that the genus $g(\Omega):=1-\chi(\Omega)$ is basically the " $n u m b e r$ of holes" inside $\Omega$, so that $\Omega$ is simply connected if and only if $\chi(\Omega)=1$.

Interestingly enough, given $p \in[1,2)$, our topological assumption on $\Omega$ is sharp in the following sense: $\left(\mathcal{E}_{p, \beta}\right)$ does not have any solution for $\beta$ sufficiently large, as soon as $\Omega$ is simply connected (see $[4,5]$ ). Yet, for $p=2$, we state the following delicate question which looks open, except in the aforementioned case of the disk:

Open problem. Let $\Omega \subset \mathbb{R}^{2}$ be a simply connected domain. Does there exists $\beta^{\sharp}>4 \pi$ such that $\left(\mathcal{E}_{\beta}\right)$ does not have any solution for $\beta>\beta^{\sharp}$ ?

To conclude this introductory part, we mention that the degree formula in Theorem 1.2 also implies the existence of blowing-up solutions for $\left(\mathcal{E}_{p, \beta}\right)$ (see Remark 2.4).

## 2. Proof of Theorems 1.1 and 1.2

Let us first notice that any nonnegative nontrivial weak $H_{0}^{1}$-solution of the PDE in $\left(\mathcal{E}_{p, \beta}\right)$ is smooth and positive in $\Omega$, as proven from Trudinger [39] with standard elliptic theory (see for instance Gilbarg-Trudinger [21]).

As a first ingredient, since the nonlinearities in the right-hand of the PDE in $\left(\mathcal{E}_{p, \beta}\right)$ are autonomous, we may use the following by-product of the moving plane technique, already used for instance by Adimurthi and Druet [1] in a similar context:

Proposition 2.1. Let $\Omega \subset \mathbb{R}^{2}$ be a smoothly bounded domain. Then there exists $\delta, \delta^{\prime}>0$ depending only on $\Omega$ such that, for any nonnegative, nondecreasing $C^{1}$ function $f:[0,+\infty) \rightarrow \mathbb{R}$, for all $v$ solving

$$
\left\{\begin{array}{l}
\Delta v=f(v), v>0 \text { in } \Omega \\
v=0 \text { on } \partial \Omega
\end{array}\right.
$$

and all $x \in \partial \Omega$, the function $t \mapsto u(x-t \nu(x))$ has positive derivative in $[0, \delta]$, where $\nu(x)$ is the unit outward normal to $\partial \Omega$ at $x$, and we have

$$
\begin{equation*}
\nabla v(x)=0 \quad \Longrightarrow \quad d(x, \partial \Omega) \geq \delta^{\prime}>0 \tag{2.1}
\end{equation*}
$$

Proof of Proposition 2.1 (completed). The existence of $\delta>0$ as in the statement of the proposition is a direct consequence of the classical moving plane argument in de Figueiredo-Lions-Nussbaum [11] if $\Omega$ is convex, while it has to be combined with Kelvin's transform in our general two-dimensional case, as observed by Han [22]. Then, since the map $(t, x) \mapsto x-t \nu(x)$ is a diffeomorphism from $[0, \delta] \times \partial \Omega$ onto a neighborhood of $\partial \Omega$ inside $\bar{\Omega}$, up to reducing $\delta>0$, (2.1) follows by compactness of $\partial \Omega$.

Proposition 2.1 is an important ingredient to take advantage of the blow-up analysis developed to get [12, Theorem 4.1] on a closed surface in our present setting of a bounded domain $\Omega$, ensuring that no new phenomena arise close to the boundary. Hence we have the following theorem:
Theorem 2.1. Let $\left(\lambda_{\varepsilon}\right)_{\varepsilon}$ be any sequence of positive real numbers and $\left(p_{\varepsilon}\right)_{\varepsilon}$ be any sequence of numbers in $[1,2]$. Let $\left(u_{\varepsilon}\right)_{\varepsilon}$ be a sequence of smooth functions solving

$$
\left\{\begin{array}{l}
\Delta u_{\varepsilon}=p_{\varepsilon} \lambda_{\varepsilon} u_{\varepsilon}^{p_{\varepsilon}-1} e^{u_{\varepsilon}^{p_{\varepsilon}}}, \quad u_{\varepsilon}>0 \text { in } \Omega  \tag{2.2}\\
u_{\varepsilon}=0 \text { on } \partial \Omega
\end{array}\right.
$$

for all $\varepsilon$. Let $\beta_{\varepsilon}$ be given by

$$
\beta_{\varepsilon}=\frac{\lambda_{\varepsilon} p_{\varepsilon}^{2}}{2}\left(\int_{\Omega}\left(e^{u_{\varepsilon}^{p_{\varepsilon}}}-1\right) d x\right)^{\frac{2-p_{\varepsilon}}{p_{\varepsilon}}}\left(\int_{\Omega} u_{\varepsilon}^{p_{\varepsilon}} e^{u_{\varepsilon}^{p_{\varepsilon}}} d x\right)^{\frac{2\left(p_{\varepsilon}-1\right)}{p_{\varepsilon}}}
$$

for all $\varepsilon$. If we assume the energy bound

$$
\lim _{\varepsilon \rightarrow 0} \beta_{\varepsilon}=\beta \in[0,+\infty)
$$

but the pointwise blow-up of the $u_{\varepsilon}$ 's, namely $\lim _{\varepsilon \rightarrow 0} \max _{\Omega} u_{\varepsilon}=+\infty$, then $\lambda_{\varepsilon} \rightarrow 0^{+}$ and there exists an integer $N \in \mathbb{N}^{\star}$ such that $\beta=4 \pi N$.

Independently, multiplying the equation in $\left(\mathcal{E}_{p, \beta}\right)$ by a first Dirichlet eigenfunction $v_{1}$ of the Laplacian, integrating by parts and using $p t^{p-1} e^{t^{p}} \geq 2 t$ for all $t \geq 0$ and $p \in[1,2]$, we get

$$
\begin{equation*}
0<2 \lambda \leq \lambda_{1} \tag{2.3}
\end{equation*}
$$

as soon as a (nontrivial) solution $u$ of $\left(\mathcal{E}_{p, \beta}\right)$ exists.
Outline of the proof of Theorem 2.1. Overall, the proof follows closely [12, Sections $2-4]$. It is even simpler in the present framework where Dirichlet boundary conditions are imposed, since we no longer need to handle the additional coercivity term $h u_{\varepsilon}$ in the left-hand $\Delta_{g} u_{\varepsilon}+h u_{\varepsilon}$ of the equation in [12, equation (4.1)] analogue to (2.2) here: indeed, all along the argument of [12], this additional term is just estimated by error terms which can be taken now to be zero.

More precisely, as pioneered by Druet [18, Sections 3-4] when $p_{\varepsilon}=2$ for all $\varepsilon$ (see also [19, Section 3]), we start with the following proposition giving a first pointwise exhaustion of the concentration points, as well as weak gradient estimates under the assumptions of Theorem 2.1:

Proposition 2.2. Up to a subsequence, there exist an integer $n \in \mathbb{N}^{\star}$ and sequences $\left(x_{i, \varepsilon}\right)_{\varepsilon}$ of points in $\Omega$ such that $\nabla u_{\varepsilon}\left(x_{i, \varepsilon}\right)=0$, such that, setting $\gamma_{i, \varepsilon}:=u_{\varepsilon}\left(x_{i, \varepsilon}\right)$,

$$
\begin{equation*}
\mu_{i, \varepsilon}:=\left(\frac{8}{\lambda_{\varepsilon} p_{\varepsilon}^{2} \gamma_{i, \varepsilon}^{2\left(p_{\varepsilon}-1\right)} e^{\gamma_{i, \varepsilon}^{p_{\varepsilon}}}}\right)^{\frac{1}{2}} \rightarrow 0 \tag{2.4}
\end{equation*}
$$

and such that

$$
\begin{equation*}
\frac{p_{\varepsilon}}{2} \gamma_{i, \varepsilon}^{p_{\varepsilon}-1}\left(\gamma_{i, \varepsilon}-u_{\varepsilon}\left(x_{i, \varepsilon}+\mu_{i, \varepsilon} \cdot\right)\right) \rightarrow T_{0}:=\ln \left(1+|\cdot|^{2}\right) \text { in } C_{l o c}^{1}\left(\mathbb{R}^{2}\right) \tag{2.5}
\end{equation*}
$$

as $\varepsilon \rightarrow 0$, for all $i \in\{1, \ldots, n\}$. Moreover, there exist $C>0$ such that we have

$$
\min _{i \in\{1, \ldots, n\}} u_{\varepsilon}^{p_{\varepsilon}-1}\left|x_{i, \varepsilon}-\cdot\right|\left|\nabla u_{\varepsilon}\right| \leq C \text { in } \Omega
$$

for all $\varepsilon$. We also have that $\lim _{\varepsilon \rightarrow 0} x_{i, \varepsilon}=x_{i}$ for all $i$, and that there exists $u_{0} \in$ $C^{2}(\bar{\Omega} \backslash \mathcal{S})$ such that

$$
\lim _{\varepsilon \rightarrow 0} u_{\varepsilon}=u_{0} \text { in } C_{l o c}^{1}(\bar{\Omega} \backslash \mathcal{S})
$$

where $\mathcal{S} \subset \Omega$ consists of all the $x_{i}$ 's.
About the concentration points $x_{i, \varepsilon}$ of this proposition, being critical points of the $u_{\varepsilon}$ 's by construction, (2.1) yields that they cannot collapse to the boundary so that proving Proposition 2.2 does not require new arguments with respect to the ones to get [12, Proposition 4.1]. In addition, (2.3) and (2.4) yield that $\gamma_{i, \varepsilon} \rightarrow+\infty$, so that (2.5) really points out a concentration profile at first order for the $u_{\varepsilon}$ 's.

But at that stage, as in [12, Section 2], the strategy is to consider a radially symmetric much more precise ansatz solving the same equation (i.e. set now $h_{0} \equiv 0$ in $[12,(2.6)]$ ), whose relevance in the non-radial setting can be quantified (see [12, Section 3] picking now $h \equiv 0$ in [12, (3.8)]). Thus assumption [12, (2.5)] and the related [12, (3.6), (3.17)-(3.19), second requirement in (3.21), (4.26), Lemma 4.1] can be now ignored. The terms $w_{l, \varepsilon}$ in $[12,(4.47)]$ and $\tilde{w}_{\varepsilon}$ in $[12,(4.85)]$ used to control this additional linear term are also now useless and we eventually do get Theorem 2.1 by following the lines of [12, Sections 2-4], since no specific new difficulty may arise close to the boundary thanks to Propositions 2.1 and 2.2. As a last important remark, the lower bound on $d\left(x_{i, \varepsilon}, \partial \Omega\right)$ from Proposition 2.2 is also used to get the key property $\lambda_{\varepsilon} \rightarrow 0^{+}$, arguing as in [12, Step 4.2].

Remark 2.1. As pointed out in [31], the positivity of the $u_{\varepsilon}$ 's is essential to have energy quantization (i.e. $\beta \in 4 \pi \mathbb{N}^{\star}$ ) in Theorem 2.1. Moreover, even restricting
to nonnegative functions, we stress that there exist Palais-Smale sequences associated to $\left(\mathcal{E}_{\beta}\right)$ with arbitrary limiting energy $\beta>4 \pi$ and converging weakly to 0 in $H_{0}^{1}$ (see Costa-Tintarev [10]), so that not only the quantization, but even the quantification proved for solutions by Druet [18] fail for general Palais-Smale sequences (see also [30] for examples with non-zero weak limit entering in the framework of [18], but where quantization fails). This is in striking constrast with a large class of otherwise closely related critical problems for which quantification already holds for Palais-Smale sequences (see for instance the pioneering work [36] by Struwe). This is maybe the clearest evidence of the huge difficulty to run directly standard variational techniques generating Palais-Smale sequences to solve $\left(\mathcal{E}_{\beta}\right)$, and motivates our compactness techniques considering only exact solutions instead of Palais-Smale sequences.

In the specific case of the mean-field equation, i.e. when $p_{\varepsilon}=1$ for all $\varepsilon$, with the same notation and assumptions as in Theorem 2.1, we obviously get

$$
\begin{equation*}
\beta_{\varepsilon}^{M F}:=\frac{\lambda_{\varepsilon}}{2} \int_{\Omega} e^{u} d x=\beta_{\varepsilon}+\frac{\lambda_{\varepsilon}|\Omega|}{2} \rightarrow \beta=4 \pi N \in 4 \pi \mathbb{N}^{\star} \tag{2.6}
\end{equation*}
$$

as $\varepsilon \rightarrow 0$. At that stage, another additional ingredient for our proof is the following result stated here with the same notation and conventions as in Theorem 1.2:
Theorem 2.2. Let $\Omega \subset \mathbb{R}^{2}$ be a smoothly bounded domain and $h \in C^{1}(\bar{\Omega})$ be positive. Let $N \in \mathbb{N}$ and $\beta \in(4 \pi N, 4 \pi(N+1))$ be given. Then the total LeraySchauder degree $d_{\beta, h}^{M F}(\Omega)$ of all the solutions of the mean-field equation

$$
\left\{\begin{array}{l}
\Delta u=\beta \frac{2 h e^{u}}{\int_{\Omega} h e^{u} d x}  \tag{MF}\\
u=0 \text { on } \partial \Omega
\end{array}\right.
$$

is well-defined and equals $\binom{N-\chi(\Omega)}{N}$.
As an obvious remark, a solution of $\left(\mathcal{E}_{\beta, h}^{M F}\right)$ has to be positive in $\Omega$. Theorem 2.2 , which is only needed here for a constant function $h>0$, has been stated first in Chen-Lin [9]. Indeed, these authors show in their beautiful work:

Proposition 2.3 (Chen-Lin [9]). For all $N \in \mathbb{N}$ and all $\beta \in(4 \pi N, 4 \pi(N+1))$, $d_{\beta, h}^{M F}(\Omega)$ is equal to a constant $d_{N}^{M F}(\Omega)$, which is 1 for $N=0$. Moreover, we have the following degree jump formula:

$$
\begin{equation*}
d_{N+1}^{M F}(\Omega)-d_{N}^{M F}(\Omega)=\frac{(-1)^{N}}{N!} \operatorname{deg}\left(\nabla \Phi_{N, h}, \Omega^{N} \backslash D_{N}, 0\right) \tag{2.7}
\end{equation*}
$$

where

$$
\begin{equation*}
\Phi_{N, h}\left(x_{1}, \ldots, x_{N}\right)=8 \pi \sum_{i \neq j} \mathcal{G}\left(x_{i}, x_{j}\right)+4 \pi \sum_{1 \leq i \leq N} \mathcal{H}\left(x_{i}, x_{i}\right)+\sum_{1 \leq i \leq N} \ln h\left(x_{i}\right) \tag{2.8}
\end{equation*}
$$

is defined in $\Omega^{N} \backslash D_{N}$ with $D_{N}:=\left\{\left(x_{1}, \ldots, x_{N}\right) \in \Omega^{N}: \exists i \neq j, x_{i}=x_{j}\right\}$, where $\mathcal{G}$ is the Green's function of $\Delta$ with zero Dirichlet boundary conditions on $\Omega$, where $\mathcal{H}$ is the regular part of $\mathcal{G}$ normalized here as

$$
\begin{equation*}
\mathcal{G}(x, y)=\frac{1}{2 \pi} \ln \frac{1}{|x-y|}+\mathcal{H}(x, y) \tag{2.9}
\end{equation*}
$$

and where $\operatorname{deg}\left(\nabla \Phi_{N, h}, \Omega^{N} \backslash D_{N}, 0\right)$ is the Brouwer degree (or total index) of the vector field $\nabla \Phi_{N, h}$.

Contrary to what occurs on a closed manifold, it turns out that, in order to compute the degree of $\nabla \Phi_{N, h}$, the classical Poincaré-Hopf formula does not directly apply in the present setting of a bounded domain since $\nabla \Phi_{N, h}$ points outwards only on a strict subset of the boundary of its domain, non-empty as soon as $N>1$. Another goal of this paper is to provide an argument showing that, for topological reasons relying strongly on the fact that every connected component of $\partial \Omega$ has zero Euler characteristic in our two-dimensional case (crucial point in Lemma 3.5, see also Remark 2.2 just below), the following formula for the degree of $\nabla \Phi_{N, h}$ holds in the present setting of a smoothly bounded domain $\Omega$, so that the degree formula in Theorem 2.2 follows from Propositions 2.3 and 2.4.

Remark 2.2. It is known that any closed odd-dimensional manifold has zero Eulercharacteristic, so that this aforementioned property for every connected boundary component of $\partial \Omega$ holds more generally for any smoothly bounded $\Omega \subset \mathbb{R}^{n}$ with $n$ even. Indeed, with minimal changes, our proof extends to this case which is relevant for instance for the fourth-order mean-field equation in Lin-Wei-Wang [27].

Proposition 2.4. The degree of $\nabla \Phi_{N, h}$ is well-defined on $\Omega^{N} \backslash D_{N}$ and one has

$$
\begin{equation*}
\operatorname{deg}\left(\nabla \Phi_{N, h}, \Omega^{N} \backslash D_{N}, 0\right)=\chi(\Omega)(\chi(\Omega)-1) \ldots(\chi(\Omega)-N+1) \tag{2.10}
\end{equation*}
$$

Proving Proposition 2.4 is the purpose of Section 3.
We are now in position to prove Theorems 1.1 and 1.2, starting with the specific case where $\beta>0$ is out of the set $4 \pi \mathbb{N}^{\star}$ of the critical energy levels.

Proof of the degree formula of Theorem 1.2 for $\beta \notin 4 \pi \mathbb{N}^{\star}$. During this whole first part, we fix $N \in \mathbb{N}$ and $\beta \in(4 \pi N, 4 \pi(N+1))$. For $t \in[0,1]$ and $p \in[1,2]$, let $T_{p, \beta}$ and $T_{t, \beta}^{M F}$ be the Fredholm-type nonlinear operators given for any non-negative non-zero function $v \in C^{1}(\bar{\Omega})$ by

$$
T_{p, \beta}(v)=v-\Delta^{-1}\left(\frac{2 \beta v^{p-1} e^{v^{p}}}{p\left(\int_{\Omega}\left(e^{v^{p}}-1\right) d x\right)^{\frac{2-p}{p}}\left(\int_{\Omega} v^{p} e^{v^{p}} d x\right)^{\frac{2(p-1)}{p}}}\right)
$$

and

$$
T_{t, \beta}^{M F}(v)=v-\Delta^{-1}\left(\frac{2 \beta e^{v}}{\int_{\Omega}\left(e^{u}-t\right) d x}\right)
$$

where $\Delta^{-1} f$ is the solution $w$ of $\Delta w=f$ with zero Dirichlet boundary conditions. By Theorem 2.1 and formula (2.6) with standard elliptic theory and (2.3), there exist constants $C>c>0$ such that

$$
\|u\|_{C^{1}(\bar{\Omega})}<C \text { and } u>c v_{1} \text { in } \Omega
$$

for all $u$ positive in $\Omega$ solving $T_{t, \beta}^{M F}(u)=0$ for some $t \in[0,1]$, and all $u$ solving $T_{p, \beta}(u)=0$, i.e. $\left(\mathcal{E}_{p, \beta}\right)$, for some $p \in[1,2]$, where $v_{1}$ is still a given first Dirichlet eigenfunction of $\Delta$ chosen positive in $\Omega$. Let $C_{0}^{1}(\bar{\Omega})$ be the closed subspace of $C^{1}(\bar{\Omega})$ consisting of the functions vanishing on $\partial \Omega$. Let $\mathcal{V}$ be the open subset of $C_{0}^{1}(\bar{\Omega})$ given by

$$
\mathcal{V}=\left\{\begin{array}{lll}
v \in C_{0}^{1}(\bar{\Omega}) \quad \text { s.t. } & v>c v_{1} \text { in } \Omega \\
\|v\|_{C^{1}(\bar{\Omega})}<C
\end{array}\right\}
$$

Using Hopf's lemma, observe that only positive functions in $\Omega$ are in the closure of $\mathcal{V}$ for the $C^{1}(\bar{\Omega})$-topology, in particular neither the zero nor any sign-changing function is in this closure. Then,

$$
(p, v) \mapsto T_{p, \beta}(v) \text { and }(t, v) \mapsto T_{t, \beta}^{M F}(v)
$$

are continuous from $[1,2] \times \mathcal{V}$ and $[0,1] \times \mathcal{V}$ respectively into $C_{0}^{1}(\bar{\Omega})$, by standard elliptic theory. Observe in particular that this continuity does hold for $T_{p, \beta}$ up to $p=1$ despite the jump of $(p, t) \in[1,2] \times(0+\infty) \mapsto p t^{p-1} e^{t^{p}}$ at $t=0^{+}$ as $p \rightarrow 1$. Using also that these operators do not vanish on the boundary of $\mathcal{V}$ by construction, the total Leray-Schauder degree $d_{p, \beta}(\Omega):=\operatorname{deg}_{L S}\left(T_{p, \beta}, \mathcal{V}, 0\right)$ (resp. $\left.d_{t, \beta}^{M F}(\Omega):=\operatorname{deg}_{L S}\left(T_{t, \beta}^{M F}, \mathcal{V}, 0\right)\right)$ of all the solutions of $\left(\mathcal{E}_{p, \beta}\right)$ (resp. of all the functions $v>0$ in $\Omega$ such that $T_{t, \beta}^{M F}(v)=0$ ) is well-defined, see for instance Nirenberg [33].
Remark 2.3. It is convenient to work here within the space $C_{0}^{1}(\bar{\Omega})$, but one could ask whether the degree thus defined coincides with the one that one could define within the natural variational space $H_{0}^{1}$. The arguments in $L i$ [26, Appendix B] slightly transposed to the present situation show that it is actually the case.
Now, for $t=0$, the formula for the total degree $d_{0, \beta}^{M F}(\Omega)$ of all the solutions of $\left(\mathcal{E}_{\beta}^{M F}\right)$ is given by Theorem 2.2. Moreover, we clearly have $T_{1, \beta}=T_{1, \beta}^{M F}$, so that $d_{1, \beta}(\Omega)=d_{1, \beta}^{M F}(\Omega)$. Using then our definition of $\mathcal{V}$, Theorem 2.2 and the homotopy invariance of the total Leray-Schauder degree as far as compactness holds, we have $d_{p, \beta}(\Omega)=d_{1, \beta}(\Omega)$ for all $p \in[1,2]$ on the one hand, while $d_{t, \beta}^{M F}(\Omega)=d_{0, \beta}^{M F}(\Omega)=$ $d_{1, \beta}^{M F}(\Omega)$ for all $t \in[0,1]$ on the other hand, which concludes the proof of Theorem 1.2 , and thus that of Theorem 1.1, in this first case where $\beta \notin 4 \pi \mathbb{N}^{\star}$.

Remark 2.4. Let $p \in[1,2]$ be fixed. A posteriori, by contraposing the homotopy invariance of the Leray-Schauder degree as far as compactness holds, observe that the effective degree jump of $d_{p, \beta}(\Omega)$ at the levels $\beta \in 4 \pi \mathbb{N}^{\star}$, as soon as the genus $g(\Omega)$ is greater than 1, imposes the existence of a sequence of blowing-up solutions with limiting energy $\beta=4 \pi N$ for all $N \in \mathbb{N}^{\star}$ as in Theorem 2.1 with $p_{\varepsilon}=p$ (see also Deng-Musso [15] or del Pino-Musso-Ruf [13, 14] for specific constructions of such blowing-up solutions for $\left.\left(\mathcal{E}_{p, \beta}\right)\right)$.

In order to complete the proof of Theorems 1.1 and 1.2, it remains to treat the case $\beta \in 4 \pi \mathbb{N}^{\star}$. This will be based on the estimate in the following theorem, saying roughly that for $p \in(1,2]$ the amount of Dirichlet energy near each blow-up point approaches $4 \pi$ from above. This estimate was first proven in the radial case and for $p=2$ by Mancini and the second author [29], then extended to the case of a bounded domain in $\mathbb{R}^{2}$ by the third author [38] (see also Ibrahim-Masmoudi-Nakanishi-Sani [23] for related results), finally on a closed two-dimensional surface [12, Theorem 5.1]. Taking Proposition 2.1 into account, the proof of [12, Theorem 5.1] can be easily adapted to yield:

Theorem 2.3. Assume $p_{\varepsilon}=p \in(1,2]$ for all $\varepsilon$ and let $u_{\varepsilon}, \lambda_{\varepsilon}, \beta_{\varepsilon} \rightarrow \beta=4 \pi N \in$ $4 \pi \mathbb{N}^{\star}$ be as in Theorem 2.1. Then

$$
\begin{equation*}
\beta_{\varepsilon} \geq 4 \pi\left(N+\frac{4(p-1)(1+o(1))}{p^{2}} \sum_{1 \leq i \leq N} \frac{1}{\gamma_{i, \varepsilon}^{2 p}}\right) \quad \text { as } \varepsilon \rightarrow 0 \tag{2.11}
\end{equation*}
$$

where the sequence $\left(\gamma_{i, \varepsilon}\right)_{\varepsilon}$ is given by Proposition 2.2 for all $i$.

Conclusion of the proof of Theorems 1.1 and 1.2. We fix now $p \in(1,2]$. Then, from Theorem 2.3 we get that $\beta_{\varepsilon}>\beta$ for all $\varepsilon$ small enough in Theorem 2.1. As a consequence, for any given $N \in \mathbb{N}$ and small $\eta \in(0,1]$, we have compactness of all the solutions of $\left(\mathcal{E}_{p, \beta}\right)$ for all $\beta \in[4 \pi(N+\eta), 4 \pi(N+1)]$. In particular, we may define as above an open neighborhood $\mathcal{V}^{\prime} \subset C_{0}^{1}(\bar{\Omega})$ containing all these solutions and whose closure contains only positive functions in $\Omega$. Then, the map $(\beta, v) \mapsto T_{p, \beta}(v)$ is continuous from $[4 \pi(N+\eta), 4 \pi(N+1)] \times \mathcal{V}^{\prime}$ to $C_{0}^{1}(\bar{\Omega})$ and, by a deformation argument as above, we get that the total Leray-Schauder degree $\operatorname{deg}_{L S}\left(T_{p, \beta}, \mathcal{V}^{\prime}, 0\right)$ of all the solutions of $\left(\mathcal{E}_{p, \beta}\right)$ is well-defined and does not depend on $\beta \in[4 \pi(N+\eta), 4 \pi(N+1)]$ : Theorems 1.1 and 1.2 are proven.

Remark 2.5. Relying now on [19], we may get a more general non-homogeneous version of Theorem 1.1, which can be stated as follows:
Theorem 2.4. Let $\Omega \subset \mathbb{R}^{2}$ be a smoothly bounded domain and $h$ be a smooth positive $C^{2}$-function in $\bar{\Omega}$. Let $F_{h}$ be given in $H_{0}^{1}$ by

$$
F_{h}(v):=\int_{\Omega}\left(e^{v^{2}}-1\right) h d x
$$

and $\mathcal{M}_{\beta} \subset H_{0}^{1}$ be as in (1.2). Assume that $\Omega$ is not contractible. Then, given any positive real number $\beta>0$, there exists a nonnegative function $u$, critical point of $F_{h}$ constrained to $\mathcal{M}_{\beta}$. In particular, $u$ is smooth and solves $\left(\mathcal{E}_{p, \beta, h}\right)$ below for $p=2$.
Proof of Theorem 2.4. We fix $p=2$. Given $\beta \in(4 \pi N, 4 \pi(N+1)]$, we claim that the total Leray-Schauder degree $d_{p, \beta, h}(\Omega)$ of the solutions of

$$
\left\{\begin{array}{l}
\Delta u=p \lambda h u^{p-1} e^{u^{p}}, u>0 \text { in } \Omega \\
u=0 \text { on } \partial \Omega \\
\frac{\lambda p^{2}}{2}\left(\int_{\Omega}\left(e^{u^{p}}-1\right) h d x\right)^{\frac{2-p}{p}}\left(\int_{\Omega} u^{p} e^{u^{p}} h d x\right)^{\frac{2(p-1)}{p}}=\beta
\end{array}\right.
$$

is well-defined and does not depend of $h$, positive $C^{2}$-function in $\bar{\Omega}$, so that it always equals $\binom{N-\chi(\Omega)}{N}$, formula given by Theorem 1.2 for $h \equiv 1$. Indeed, first given $\beta>0$ out of $4 \pi \mathbb{N}^{\star}$, it follows from the quantization and the associated compactness result in [19] that $d_{p, \beta, h_{r}}(\Omega)$ is well-defined and does not depend of $r \in[0,1]$, where $h_{r}=(1-r)+r h$. Fixing now such an $h, N \in \mathbb{N}$ and $\eta \in(0,1]$ and using that boundary blow-up cannot either occur for the solutions of $\left(\mathcal{E}_{p, \beta, h}\right)$ (see Remark 2.6 just below), the energy estimate in Theorem 2.3 from [12, Section 5] still holds here and gives the compactness of all the solutions of $\left(\mathcal{E}_{p, \beta, h}\right)$ for all $\beta \in[4 \pi(N+\eta), 4 \pi(N+1)]$, so that $d_{p, \beta, h}(\Omega)$ does not depend on $\beta$ in this range by following the second part of the above proof: Theorem 2.4 is proven.

Remark 2.6. Excluding boundary blow-up is actually the most delicate part in [19] where $p$ is fixed equal to 2. The analogue property appears to be open for $p \in(1,2)$.
3. Degree formula for the vector field associated to $\mathcal{E}_{\beta, h}^{M F}$ on a BOUNDED DOMAIN $\Omega$

The purpose of this section is to prove Proposition 2.4. Let $\mathcal{G}$ be the Green's function of $\Delta$ with zero Dirichlet boundary conditions and $\mathcal{H}$ be its regular part with the convention in (2.9). Given $y \in \Omega$, notice that

$$
\mathcal{G}(x, y) \rightarrow+\infty \quad \text { as } x \rightarrow y \quad \text { and that } \quad \mathcal{H}(x, x) \rightarrow-\infty \quad \text { as } x \rightarrow \partial \Omega .
$$

Given a positive function $h \in C^{1}(\bar{\Omega})$, let $\Phi_{N, h}$ be given by (2.8). To fix the notation, we will write

$$
\nabla \Phi_{N, h}\left(x_{1}, \ldots, x_{N}\right)=\left(\nabla_{x_{1}} \Phi_{N, h}\left(x_{1}, \ldots, x_{N}\right), \ldots, \nabla_{x_{N}} \Phi_{N, h}\left(x_{1}, \ldots, x_{N}\right)\right)
$$

with

$$
\nabla_{x_{j}} \Phi_{N, h}\left(x_{1}, \ldots, x_{N}\right)=16 \pi \sum_{\substack{1 \leq \ell \leq N \\ \ell \neq j}} \nabla \mathcal{G}\left(x_{j}, x_{\ell}\right)+8 \pi \nabla \mathcal{H}\left(x_{j}, x_{j}\right)+\frac{\nabla h\left(x_{j}\right)}{h\left(x_{j}\right)}
$$

where we denote by $\nabla \mathcal{G}(x, y)$ and $\nabla \mathcal{H}(x, y)$ the gradient with respect to the first variable.

In order to get Proposition 2.4, we first need to analyse the compactness of the critical points of $\Phi_{N, h}$.
3.1. Compactness of critical points of $\Phi_{N, h}$. In this subsection we prove that, uniformly with respect to $t \in[0,1]$, critical the points of

$$
\Phi_{N, h}^{t}\left(x_{1}, \ldots, x_{N}\right):=8 \pi \sum_{\substack{1 \leq i, j \leq N \\ i \neq j}} \mathcal{G}\left(x_{i}, x_{j}\right)+4 \pi \sum_{1 \leq i \leq N} \mathcal{H}\left(x_{i}, x_{i}\right)+t \sum_{1 \leq i \leq N} \ln h\left(x_{i}\right)
$$

cannot be arbitrarily close to the boundary of $\Omega^{N} \backslash D_{N}$, implying that the degree in Proposition 2.4 is well-defined. More precisely, define

$$
\begin{array}{r}
\left(\Omega^{N} \backslash D_{N}\right)_{\delta}:=\left\{\left(x_{1}, \ldots, x_{N}\right) \in \Omega^{N} \backslash D_{N}:\left|x_{i}-x_{j}\right|>\delta \text { for } 1 \leq i<j \leq N\right. \\
\left.d\left(x_{i}, \partial \Omega\right)>\delta \text { for } 1 \leq i \leq N\right\} \tag{3.1}
\end{array}
$$

Lemma 3.1. For every $M>0$, there exists $\delta>0$ such that
$\left|\nabla \Phi_{N, h}^{t}\left(x_{1}, \ldots, x_{N}\right)\right| \geq M, \quad$ for $\left(x_{1}, \ldots, x_{N}\right) \in\left(\Omega^{N} \backslash D_{N}\right) \backslash\left(\Omega^{N} \backslash D_{N}\right)_{\delta}, t \in[0,1]$.
As a consequence, the degree of $\nabla \Phi_{N, h}^{t}$ is well-defined on $\Omega^{N} \backslash D_{N}$ as

$$
\operatorname{deg}\left(\nabla \Phi_{N, h}, \Omega^{N} \backslash D_{N}, 0\right):=\operatorname{deg}\left(\nabla \Phi_{N, h}, A, 0\right)
$$

for any open set $A$ with $\left(\Omega^{N} \backslash D_{N}\right)_{\delta} \subset A \subset \Omega^{N} \backslash D_{N}$.
Proof. Consider sequences

$$
\left(t_{k}\right)_{k \in \mathbb{N}} \subset[0,1], \quad\left(x_{1, k}, \ldots, x_{N, k}\right)_{k \in \mathbb{N}} \subset \Omega^{N} \backslash D_{N}
$$

such that

$$
\begin{equation*}
\nabla \Phi_{N, h}^{t_{k}}\left(x_{1, k}, \ldots, x_{N, k}\right)=O(1), \quad \text { as } k \rightarrow \infty \tag{3.2}
\end{equation*}
$$

Set

$$
\begin{equation*}
r_{i, k}:=\min \left\{d_{i, k}, \min _{j \neq i}\left|x_{i, k}-x_{j, k}\right|\right\}, \quad d_{i, k}:=d\left(x_{i, k}, \partial \Omega\right) \tag{3.3}
\end{equation*}
$$

Up to extracting a subsequence and reordering the indices we can assume that

$$
\begin{equation*}
r_{1, k} \leq r_{j, k}, \quad \text { for } 1 \leq j \leq N \tag{3.4}
\end{equation*}
$$

and set

$$
\begin{equation*}
r_{k}:=r_{1, k}, \quad x_{k}:=x_{1, k}, \quad d_{k}:=d_{1, k} \tag{3.5}
\end{equation*}
$$

It suffices to prove that $\liminf _{k \rightarrow \infty} r_{k}>0$. Then we assume, by contradiction, that

$$
\begin{equation*}
\lim _{k \rightarrow \infty} r_{k}=0 \tag{3.6}
\end{equation*}
$$

We now scale the domain $\Omega$ and the functional $\Phi_{N, h}^{t_{k}}$ at $x_{k}$ by a factor $r_{k}$. More precisely, we set $\Omega_{k}:=r_{k}^{-1}\left(\Omega-x_{k}\right)$ and, for $\left(z_{1}, \ldots, z_{N}\right) \in \Omega_{k}^{N} \backslash D_{N}$, we define

$$
\begin{aligned}
\Xi_{k}\left(z_{1}, \ldots, z_{N}\right) & =\Phi_{N, h}^{t_{k}}\left(x_{k}+r_{k} z_{1}, \ldots, x_{k}+r_{k} z_{N}\right) \\
& =8 \pi \sum_{\substack{1 \leq i, j \leq N \\
i \neq j}} \mathcal{G}_{k}\left(z_{i}, z_{j}\right)+4 \pi \sum_{1 \leq i \leq N} \mathcal{H}_{k}\left(z_{i}, z_{i}\right)+t_{k} \sum_{1 \leq i \leq N} \ln h_{k}\left(z_{i}\right)
\end{aligned}
$$

where $\mathcal{G}_{k}$ and $\mathcal{H}_{k}$ are the Green's function of $\Delta$ on $\Omega_{k}$ and its regular part, and $h_{k}(z):=h\left(x_{k}+r_{k} z\right)$. Then (3.2) gives

$$
\begin{equation*}
\nabla \Xi_{k}\left(z_{1, k}, \ldots, z_{N, k}\right)=O\left(r_{k}\right), \quad \text { as } k \rightarrow \infty \tag{3.7}
\end{equation*}
$$

where

$$
\left(z_{1, k}, \ldots, z_{N, k}\right):=\left(r_{k}^{-1}\left(x_{1, k}-x_{k}\right), \ldots, r_{k}^{-1}\left(x_{N, k}-x_{k}\right)\right)
$$

Up to a further subsequence we set

$$
\begin{equation*}
\mathcal{D}:=\left\{i \in\{1, \ldots, N\}:\left|x_{i, k}-x_{k}\right|=O\left(r_{k}\right) \text { as } k \rightarrow \infty\right\} \tag{3.8}
\end{equation*}
$$

and have

$$
\begin{equation*}
\lim _{k \rightarrow \infty} \frac{\left|x_{i, k}-x_{k}\right|}{r_{k}}=+\infty \quad \text { for } i \in\{1, \ldots, N\} \backslash \mathcal{D} \tag{3.9}
\end{equation*}
$$

Clearly $\mathcal{D} \neq \emptyset$, since $1 \in \mathcal{D}$. Define also, up to a subsequence,

$$
Z^{\prime}=\left(z_{i}\right)_{i \in \mathcal{D}}, \quad Z_{k}^{\prime}=\left(z_{i, k}\right)_{i \in \mathcal{D}} \rightarrow Z_{\infty}^{\prime}=\left(z_{i, \infty}\right)_{i \in \mathcal{D}}, \quad \text { as } k \rightarrow \infty
$$

Notice that (3.3) and (3.8) imply

$$
\begin{equation*}
\frac{1}{C} r_{k} \leq\left|x_{i, k}-x_{j, k}\right| \leq C r_{k} \quad \text { for } i, j \in \mathcal{D}, \quad i \neq j \tag{3.10}
\end{equation*}
$$

and in particular $z_{i, \infty} \neq z_{j, \infty}$ for $i, j \in \mathcal{D}, i \neq j$. We now define the "reduced" functional

$$
\begin{align*}
\Xi_{\mathcal{D}, k}\left(z_{1}, \ldots, z_{N}\right):= & 8 \pi \sum_{\substack{i, j \in \mathcal{D} \\
i \neq j}} \mathcal{G}_{k}\left(z_{i}, z_{j}\right)+4 \pi \sum_{i \in \mathcal{D}} \mathcal{H}_{k}\left(z_{i}, z_{i}\right)+t_{k} \sum_{i \in \mathcal{D}} \ln h_{k}\left(z_{i}\right) \\
& +16 \pi \sum_{i \in \mathcal{D}} \sum_{\substack{\leq j \leq N \\
j \notin \mathcal{D}}} \mathcal{G}_{k}\left(z_{i}, z_{j}\right) . \tag{3.11}
\end{align*}
$$

From (3.7) we get

$$
\begin{equation*}
\nabla_{Z^{\prime}} \Xi_{\mathcal{D}, k}\left(z_{1, k}, \ldots, z_{N, k}\right)=O\left(r_{k}\right) \tag{3.12}
\end{equation*}
$$

Taking (3.6) into account, we now consider 2 cases.
Case 1. Assume that, up to a subsequence,

$$
\begin{equation*}
r_{k}=o\left(d_{k}\right) \quad \text { as } k \rightarrow \infty \tag{3.13}
\end{equation*}
$$

Then $\Omega_{k}$ invades $\mathbb{R}^{2}$ as $k \rightarrow \infty$ and, choosing $K \subset \mathbb{R}^{2}$ compact containing $z_{i, k}$ for $i \in \mathcal{D}$ and $k$ large, we get from Lemma A. 1

$$
\begin{aligned}
\nabla \mathcal{G}_{k}\left(z_{i, k}, z_{j, k}\right) & =\frac{1}{2 \pi} \nabla \ln \frac{1}{\left|z_{i, k}-z_{j, k}\right|}+O\left(\frac{r_{k}}{d_{k}}\right), \quad \text { for } i, j \in \mathcal{D} \\
\nabla \mathcal{G}_{k}\left(z_{i, k}, z_{j, k}\right) & =\frac{1}{2 \pi} \nabla \ln \frac{1}{\left|z_{i, k}-z_{j, k}\right|}+O\left(\frac{r_{k}}{d_{k}}\right)=o(1), \quad \text { for } i \in \mathcal{D}, j \notin \mathcal{D}, \\
\nabla \mathcal{H}_{k}\left(z_{i, k}, z_{i, k}\right) & =O\left(\frac{r_{k}}{d_{k}}\right) \quad \text { for } i \in \mathcal{D}
\end{aligned}
$$

as $k \rightarrow \infty$. Moreover $\nabla \ln h_{k}\left(z_{i, k}\right)=O\left(r_{k}\right)$ as $k \rightarrow \infty$ for $i \in \mathcal{D}$. Then from (3.11) and (3.12) we infer

$$
\begin{equation*}
\nabla \Xi_{\mathcal{D}, \mathbb{R}^{2}}\left(Z_{k}^{\prime}\right)=o(1), \quad \text { as } k \rightarrow \infty \tag{3.14}
\end{equation*}
$$

where

$$
\begin{equation*}
\Xi_{\mathcal{D}, \mathbb{R}^{2}}\left(Z^{\prime}\right):=4 \sum_{\substack{i, j \in \mathcal{D} \\ i \neq j}} \ln \frac{1}{\left|z_{i}-z_{j}\right|} \tag{3.15}
\end{equation*}
$$

Notice that, thanks to (3.3), (3.8) and (3.13), we have $\mathcal{D} \cap\{2, \ldots, N\} \neq \emptyset$. Since also $1 \in \mathcal{D}$, the sum in (3.15) is non-empty. Letting now $k \rightarrow \infty$ in (3.14) it follows that $\nabla \Xi_{\mathcal{D}, \mathbb{R}^{2}}\left(Z_{\infty}^{\prime}\right)=0$. This contradicts Lemma A.3.

Case 2. Assume that we are not in Case 1. Then since $r_{k} \leq d_{k}$, we have up to a subsequence

$$
\frac{d_{k}}{r_{k}} \rightarrow L \geq 1, \quad \text { as } k \rightarrow \infty
$$

Then, up to a rotation, $\Omega_{k}$ converges to the half-space $H=\left\{(x, y) \in \mathbb{R}^{2}: y<L\right\}$. Let $\mathcal{G}_{H}$ and $\mathcal{H}_{H}$ be the Green's function on $H$ and its regular part, as given explicitly in the appendix. Choosing $K \subset H$ compact containing $z_{i, k}$ for $i \in \mathcal{D}$ and $k$ large, by Lemma A. 2 we estimate

$$
\begin{aligned}
\nabla \mathcal{G}_{k}\left(z_{i, k}, z_{j, k}\right) & =\nabla \mathcal{G}_{H}\left(z_{i, k}, z_{j, k}\right)+O\left(r_{k}\right), \quad \text { for } i, j \in \mathcal{D} \\
\nabla \mathcal{G}_{k}\left(z_{i, k}, z_{j, k}\right) & =o(1), \quad \text { for } i \in \mathcal{D}, j \notin \mathcal{D} \\
\nabla \mathcal{H}_{k}\left(z_{i, k}, z_{i, k}\right) & =\nabla \mathcal{H}_{H}\left(z_{i, k}, z_{i, k}\right)+O\left(r_{k}\right) \quad \text { for } i \in \mathcal{D}
\end{aligned}
$$

and $\nabla \ln h_{k}\left(z_{i, k}\right)=O\left(r_{k}\right)$ as $k \rightarrow \infty$ for $i \in \mathcal{D}$, hence, from (3.11) and (3.12) we obtain

$$
\begin{equation*}
\nabla \Xi_{\mathcal{D}, H}\left(Z_{k}^{\prime}\right)=o(1), \quad \text { as } k \rightarrow \infty \tag{3.16}
\end{equation*}
$$

where

$$
\Xi_{\mathcal{D}, H}\left(Z^{\prime}\right):=8 \pi \sum_{\substack{i, j \in \mathcal{D} \\ i \neq j}} \mathcal{G}_{H}\left(z_{i}, z_{j}\right)+4 \pi \sum_{i \in \mathcal{D}} \mathcal{H}_{H}\left(z_{i}, z_{i}\right)
$$

Letting $k \rightarrow \infty$ in (3.16) we get $\nabla \Xi_{\mathcal{D}, H}\left(Z_{\infty}^{\prime}\right)=0$, contradicting Lemma A.5.
These contradictions, arising from assumptions (3.2) and (3.6), complete the proof of the lemma.

A first consequence of Lemma 3.1 is that the degree of $\Phi_{N, h}$ does not depend on $h$, so that in the following we will work with $h \equiv 1$.

Corollary 3.1. We have

$$
\operatorname{deg}\left(\nabla \Phi_{N, h}, \Omega^{N} \backslash D_{N}, 0\right)=\operatorname{deg}\left(\nabla \Phi_{N}, \Omega^{N} \backslash D_{N}, 0\right)
$$

where, for $\left(x_{1}, \ldots, x_{N}\right) \in \Omega^{N} \backslash D_{N}$,

$$
\Phi_{N}\left(x_{1}, \ldots, x_{N}\right):=8 \pi \sum_{\substack{1 \leq i, j \leq N \\ i \neq j}} \mathcal{G}\left(x_{i}, x_{j}\right)+4 \pi \sum_{1 \leq i \leq N} \mathcal{H}\left(x_{i}, x_{i}\right)
$$

Proof. We can deform $\Phi_{N, h}=\Phi_{N, h}^{1}$ into $\Phi_{N}=\Phi_{N, h}^{0}$ and use the invariance of the degree under homotopy, since for $\delta$ sufficiently small and $t \in[0,1], \Phi_{N, h}^{t}$ has no critical points on $\partial\left(\Omega^{N} \backslash D_{N}\right)_{\delta}$.
3.2. Bending the Robin function to apply the Poincaré-Hopf theorem. Since we will not be able to apply the theorem of Poincaré-Hopf directly to $\nabla \Phi_{N}$ to compute $\operatorname{deg}\left(\nabla \Phi_{N}, \Omega^{N} \backslash D_{N}, 0\right)$, as $\nabla \Phi_{N}$ does not always point outwards near $\partial\left(\Omega^{N} \backslash D_{N}\right)$, we now introduce a modified function $\tilde{\Phi}_{N}$ by bending the function $\mathcal{H}(y, y)$ upwards near the boundary of $\Omega$, in order to obtain a function that tends to $+\infty$ on $\partial\left(\Omega^{N} \backslash D_{N}\right)$. More precisely, let $\tau \in C^{\infty}([0, \infty))$ be a non-decreasing function such that

$$
\tau(t)=1 \quad \text { for } t \geq \frac{1}{2}, \quad \tau(t)=-1 \quad \text { for } t \leq \frac{1}{4}
$$

and set

$$
\begin{equation*}
\tilde{\mathcal{H}}(x):=\mathcal{H}(x, x) \tau\left(\frac{d(y, \partial \Omega)}{\tilde{\delta}}\right) \tag{3.17}
\end{equation*}
$$

see Figure 1. Let then $\tilde{\Phi}_{N}$ be given in $\Omega^{N} \backslash D_{N}$ by


Figure 1. Heuristic sketch of $\tilde{\mathcal{H}}$ near $\partial \Omega$

$$
\begin{equation*}
\tilde{\Phi}_{N}\left(x_{1}, \ldots, x_{N}\right)=8 \pi \sum_{\substack{1 \leq i, j \leq N \\ i \neq j}} \mathcal{G}\left(x_{i}, x_{j}\right)+4 \pi \sum_{1 \leq i \leq N} \tilde{\mathcal{H}}\left(x_{i}\right) . \tag{3.18}
\end{equation*}
$$

We next show that for $0<\delta^{\prime}<\delta / 2$ and for $\tilde{\delta}$ sufficiently small (depending on $\left.\delta^{\prime}\right)$, the topological strips determined by $\delta^{\prime}<d(y, \partial \Omega)<\delta$ is a forbidden zone for critical points of $\tilde{\Phi}$, as made precise in the following lemma.

Lemma 3.2. For every $M^{\prime}>0$ there exist $\delta>0$, such that for any $\delta^{\prime} \in(0, \delta / 2)$ there exists $\tilde{\delta} \in\left(0, \delta^{\prime} / 2\right)$ such that, setting $\tilde{\Phi}_{N}$ depending on $\tilde{\delta}$ as in (3.17)-(3.18), we have

$$
\left|\nabla \tilde{\Phi}_{N}\left(x_{1}, \ldots, x_{N}\right)\right| \geq M^{\prime}
$$

if $\left(x_{1}, \ldots, x_{N}\right) \in \Omega^{N} \backslash D_{N}$ is such that $\delta^{\prime} \leq d\left(x_{i}, \partial \Omega\right) \leq \delta$ for some $1 \leq i \leq N$. In particular, if $\left(x_{1}, \ldots, x_{N}\right)$ is a critical point of $\tilde{\Phi}_{N}$, then either $d\left(x_{i}, \partial \Omega\right)>\delta$ or $d\left(x_{i}, \partial \Omega\right)<\delta^{\prime}$ for every $i=1, \ldots, N$.

Proof. Fix $M^{\prime}>0$ and let $\delta:=\min _{1 \leq I \leq N} \delta_{I}$, where $\delta_{I}$ is the constant $\delta$ appearing in Lemma 3.1 applied with $N$ replaced by $I$ and with $M=M^{\prime}+1>0$.

Assuming by contradiction that the lemma is false, we can find $\delta^{\prime} \in(0, \delta / 2)$, and sequences $\tilde{\delta}_{k} \rightarrow 0$ and $\left(x_{1, k}, \ldots, x_{N, k}\right) \subset \Omega^{N} \backslash D_{N}$ such that, for $\tilde{\Phi}_{N, k}$ defined using $\tilde{\delta}_{k}$, we have

$$
\begin{equation*}
\left|\nabla \tilde{\Phi}_{N, k}\left(x_{1, k}, \ldots, x_{N, k}\right)\right|<M^{\prime} \quad \text { as } k \rightarrow \infty \tag{3.19}
\end{equation*}
$$

and such that, up to relabelling,

$$
\begin{equation*}
\delta^{\prime} \leq d\left(x_{1, k}, \partial \Omega\right) \leq \delta \tag{3.20}
\end{equation*}
$$

Up to passing to subsequence and a further relabelling, let $I \in\{1, \ldots, N\}$ such that

$$
\begin{equation*}
\lim _{k \rightarrow \infty} d\left(x_{i, k}, \partial \Omega\right)>0 \quad \text { for } 1 \leq i \leq I \tag{3.21}
\end{equation*}
$$

and

$$
\lim _{k \rightarrow \infty} d\left(x_{j, k}, \partial \Omega\right)=0, \quad I+1 \leq j \leq N
$$

By (3.20) and Lemma 3.1 we have

$$
\begin{equation*}
\left|\nabla \Phi_{I}\left(x_{1, k}, \ldots, x_{I, k}\right)\right| \geq M^{\prime}+1 \tag{3.22}
\end{equation*}
$$

where

$$
\Phi_{I}\left(x_{1}, \ldots, x_{I}\right):=8 \pi \sum_{\substack{1 \leq i, j \leq I \\ i \neq j}} \mathcal{G}\left(x_{i}, x_{j}\right)+4 \pi \sum_{1 \leq i \leq I} \mathcal{H}\left(x_{i}, x_{i}\right)
$$

Observe, on the other, hand that

$$
\begin{equation*}
\nabla \mathcal{G}\left(x_{i, k}, x_{j, k}\right)=o(1), \quad 1 \leq i \leq I, \quad I+1 \leq j \leq N \tag{3.23}
\end{equation*}
$$

with $o(1) \rightarrow 0$ as $k \rightarrow \infty$ (since $x_{j, k}$ is approaching $\partial \Omega$, while $x_{i, k}$ is not as $k \rightarrow \infty$ ). Then, by (3.21), for $k$ large enough (hence $\tilde{\delta}_{k}$ sufficiently small), we have

$$
\begin{aligned}
\tilde{\Phi}_{N, k}\left(x_{1, k}, \ldots, x_{N, k}\right)= & \Phi_{I}\left(x_{1, k}, \ldots, x_{I, k}\right)+16 \pi \sum_{\substack{1 \leq i \leq I \\
I+1 \leq j \leq N}} \mathcal{G}\left(x_{i, k}, x_{j, k}\right) \\
& +8 \pi \sum_{I+1 \leq i, j \leq N} \mathcal{G}\left(x_{i, k}, x_{j, k}\right)+4 \pi \sum_{I+1 \leq J \leq N} \tilde{\mathcal{H}}_{k}\left(x_{j, k}\right) .
\end{aligned}
$$

Then, setting $X^{\prime}:=\left(x_{1}, \ldots, x_{I}\right)$, from (3.19), (3.22) and (3.23) we get

$$
\begin{aligned}
M^{\prime} & >\left|\nabla_{X^{\prime}}, \tilde{\Phi}_{N, k}\left(x_{1, k}, \ldots, x_{N, k}\right)\right|=\left|\nabla \Phi_{I}\left(x_{1, k}, \ldots, x_{I, k}\right)\right|+o(1) \\
& \geq M^{\prime}+1+o(1)
\end{aligned}
$$

giving a contradiction for $k$ large enough.
We now have the analog of Lemma 3.1 for $\tilde{\Phi}_{N}$.
Lemma 3.3. For every $M^{\prime \prime}>0$ there exists $\delta^{\prime \prime} \leq \frac{\tilde{\delta}}{2}$ depending on $\tilde{\delta}$ and $M^{\prime \prime}$ such that

$$
\left|\nabla \tilde{\Phi}_{N}\left(x_{1}, \ldots, x_{N}\right)\right| \geq M^{\prime \prime}
$$

for every $\left(x_{1}, \ldots, x_{N}\right) \in\left(\Omega^{N} \backslash D_{N}\right) \backslash\left(\Omega^{N} \backslash D_{N}\right)_{\delta^{\prime \prime}}$. In particular, all the critical points of $\nabla \tilde{\Phi}_{N}$ are in $\left(\Omega^{N} \backslash D_{N}\right)_{\delta^{\prime \prime}}$ and we can define

$$
\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Omega^{N} \backslash D_{N}, 0\right):=\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, A, 0\right)
$$

for any open set $A$ such that $\left(\Omega^{N} \backslash D_{N}\right)_{\delta^{\prime \prime}} \subset A \subset \Omega^{N} \backslash D_{N}$.

Proof. The proof by contradiction is essentially identical to the proof of Lemma 3.1, upon noticing the following facts. In Case 1 , namely $r_{k}=o\left(d_{k}\right)$, if (up to a subsequence) $d_{k} \rightarrow 0$ as $k \rightarrow \infty$, then

$$
\tilde{\mathcal{H}}\left(x_{i, k}\right)=-\mathcal{H}\left(x_{i, k}, x_{i, k}\right) \quad \text { for } i \in \mathcal{D}, \quad k \text { large },
$$

hence

$$
\nabla \tilde{\mathcal{H}}_{k}\left(z_{i, k}\right)=-\nabla \mathcal{H}_{k}\left(z_{i, k}, z_{i, k}\right)=O\left(r_{k}\right), \quad \text { for } i \in \mathcal{D}, \quad k \text { large }
$$

If $d_{k} \nrightarrow 0$, from (3.17), we bound

$$
\left|\nabla \tilde{\mathcal{H}}\left(x_{i, k}\right)\right|=O\left(\nabla \mathcal{H}\left(x_{i, k}, x_{i, k}\right)+C_{\tilde{\delta}}\left|\mathcal{H}\left(x_{i, k}, x_{i, k}\right)\right|\right)=O(1), \quad \text { as } k \rightarrow \infty, \quad i \in \mathcal{D}
$$

hence again $\nabla \tilde{\mathcal{H}}_{k}\left(z_{i, k}\right)=O\left(r_{k}\right)$ as $k \rightarrow \infty$ for $i \in \mathcal{D}$, where $\tilde{\mathcal{H}}_{k}(z):=\tilde{\mathcal{H}}\left(x_{k}+\right.$ $\left.r_{k} z\right)$. Then, up to a subsequence, $Z_{k}^{\prime}$ converges to $Z_{\infty}^{\prime}$, a critical point of $\Xi_{\mathcal{D}, \mathbb{R}^{2}}$, contradicting Lemma A.3.

In Case 2, since $d\left(x_{1, k}, \partial \Omega\right) \rightarrow 0$, we also have $d\left(x_{i, k}, \partial \Omega\right) \rightarrow 0$ as $k \rightarrow \infty$ for $i \in \mathcal{D}$, hence $\tilde{\mathcal{H}}\left(x_{i, k}\right)=-\mathcal{H}\left(x_{i, k}, x_{i, k}\right)$ for $i \in \mathcal{D}$ and $k$ large enough. Then, setting $\Xi_{\mathcal{D}, k}^{-}$as in (3.11) with $h_{k} \equiv 1$ and $\mathcal{H}_{k}\left(z_{i}, z_{i}\right)$ replaced by $-\mathcal{H}_{k}\left(z_{i}, z_{i}\right)$, we obtain $\nabla \Xi_{\mathcal{D}, H}^{-}\left(Z_{\infty}^{\prime}\right)=0$, where

$$
\Xi_{\mathcal{D}, H}^{-}\left(Z^{\prime}\right):=8 \pi \sum_{\substack{i, j \in \mathcal{D} \\ i \neq j}} \mathcal{G}_{H}\left(z_{i}, z_{j}\right)-4 \pi \sum_{i \in \mathcal{D}} \mathcal{H}_{H}\left(z_{i}, z_{i}\right)
$$

contradicting Lemma A.5.
We recall next a variant of the classical Poincaré-Hopf index theorem, which can be found e.g. in [7], pages 99-104 (here we adapt the statement to our purposes).

Proposition 3.1. Let $U \subset \mathbb{R}^{n}$ be an open set and consider $f \in C^{2}(U, \mathbb{R})$. Assume also that, for some $b \in \mathbb{R}, f^{b}:=\{x \in U: f(x)<b\}$ has compact closure, and that $f$ has no critical points in $f^{-1}(b)$. Then we have

$$
\begin{equation*}
\operatorname{deg}\left(\nabla f, f^{b}, 0\right)=\chi\left(f^{b}\right) \tag{3.24}
\end{equation*}
$$

Lemma 3.4. We have

$$
\begin{equation*}
\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Omega^{N} \backslash D_{N}, 0\right)=\chi(\Omega)(\chi(\Omega)-1) \ldots(\chi(\Omega)-N+1) \tag{3.25}
\end{equation*}
$$

Proof. Since

$$
\lim _{\left(x_{1}, \ldots, x_{N}\right) \rightarrow \partial\left(\Omega^{N} \backslash D_{N}\right)} \tilde{\Phi}_{N}\left(x_{1}, \ldots, x_{N}\right)=+\infty
$$

we can take $b>0$ large enough such that

$$
\left(\Omega^{N} \backslash D_{N}\right)_{\delta^{\prime \prime}} \subset\left(\tilde{\Phi}_{N}\right)^{b}
$$

where $\delta^{\prime \prime}$ is as in Lemma 3.3 with $M^{\prime \prime}=1$. Then, since $\left(\Omega^{N} \backslash D_{N}\right) \backslash\left(\tilde{\Phi}_{N}\right)^{b}$ contains no critical points of $\tilde{\Phi}_{N}$ by Lemma 3.3, we can apply Proposition 3.1 to get

$$
\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Omega^{N} \backslash D_{N}, 0\right)=\operatorname{deg}\left(\nabla \tilde{\Phi}_{N},\left(\tilde{\Phi}_{N}\right)^{b}, 0\right)=\chi\left(\left(\tilde{\Phi}_{N}\right)^{b}\right)
$$

Since $\left(\Omega^{N} \backslash D_{N}\right) \backslash\left(\tilde{\Phi}_{N}\right)^{b}$ contains no critical points of $\tilde{\Phi}_{N}$, we can use a gradient flow to retract $\left(\Omega^{N} \backslash D_{N}\right)$ to $\left(\tilde{\Phi}_{N}\right)^{b}$. Therefore $\chi\left(\left(\tilde{\Phi}_{N}\right)^{b}\right)=\chi\left(\Omega^{N} \backslash D_{N}\right)$, and we conclude with Proposition B. 1 below.


Figure 2. $\left(x_{1}, \ldots, x_{N}\right) \in \Theta_{\delta, \delta^{\prime}, I}^{*}=\left(\left(\Omega_{\delta}\right)^{I} \backslash D_{I}\right) \times\left(\left(\Sigma_{\delta^{\prime}}\right)^{N-I} \backslash D_{N-I}\right)$
3.3. Counting the new critical points. By bending the Robin function we have in general created new critical points near the boundary. In this section we will show that these new critical points do not change the total degree. To this purpose, we now define the following sets (see Figure 2):

$$
\Omega_{\delta}:=\{y \in \Omega: d(y, \partial \Omega)>\delta\} ; \quad \Sigma_{\delta^{\prime}}:=\Omega \backslash \bar{\Omega}_{\delta^{\prime}},
$$

and for $0 \leq I \leq N$

$$
\begin{aligned}
\Theta_{\delta, \delta^{\prime}, I}^{*}= & \left\{\left(x_{1}, \ldots, x_{N}\right) \in \Omega^{N} \backslash D_{N}: x_{1}, \ldots, x_{I} \in \Omega_{\delta}, x_{I+1}, \ldots, x_{N} \in \Sigma_{\delta^{\prime}}\right\} \\
= & \left(\left(\Omega_{\delta}\right)^{I} \backslash D_{I}\right) \times\left(\left(\Sigma_{\delta^{\prime}}\right)^{N-I} \backslash D_{N-I}\right) ; \\
\Theta_{\delta, \delta^{\prime}, I}= & \left\{\left(x_{1}, \ldots, x_{N}\right) \in \Omega^{N} \backslash D_{N}:\left(x_{\sigma(1)}, \ldots, x_{\sigma(N)}\right) \in \Theta_{\delta, \delta^{\prime}, I}^{*}\right. \\
& \text { for a permutation } \left.\sigma \in S_{N}\right\} ; \\
\Theta_{\delta, \delta^{\prime}, \delta^{\prime}, I}^{*}= & \Theta_{\delta, \delta^{\prime}, I}^{*} \cap\left(\Omega^{N} \backslash D_{N}\right)_{\delta^{\prime \prime}}, \quad \Theta_{\delta, \delta^{\prime}, \delta^{\prime \prime}, I}=\Theta_{\delta, \delta^{\prime}, I} \cap\left(\Omega^{N} \backslash D_{N}\right)_{\delta^{\prime \prime}} .
\end{aligned}
$$

By Lemmata 3.2 and 3.3, we can define for $0 \leq I \leq N-1$

$$
\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Theta_{\delta, \delta^{\prime}, I}, 0\right):=\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, A, 0\right)
$$

for any open set $A$ such that $\Theta_{\delta, \delta^{\prime}, \delta^{\prime \prime}, I} \subset A \subset \Theta_{\delta, \delta^{\prime}, I}$. Moreover, there are no critical points of $\tilde{\Phi}_{N}$ in $\left(\Omega^{N} \backslash D_{N}\right) \backslash \cup_{I=0}^{N} \Theta_{\delta, \delta^{\prime}, I}$ by Lemma 3.2; therefore by the excision property and noting that $\Theta_{\delta, \delta^{\prime}, N}=\left(\Omega_{\delta}\right)^{N} \backslash D_{N}$ and that $\tilde{\Phi}_{N}=\Phi_{N}$ inside $\left(\Omega_{\delta}\right)^{N} \backslash D_{N}$, we have

$$
\begin{align*}
\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Omega^{N} \backslash D_{N}, 0\right) & =\operatorname{deg}\left(\nabla \Phi_{N},\left(\Omega_{\delta}\right)^{N} \backslash D_{N}, 0\right)+\sum_{I=0}^{N-1} \operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Theta_{\delta, \delta^{\prime}, I}, 0\right) \\
= & \operatorname{deg}\left(\nabla \Phi_{N},\left(\Omega_{\delta}\right)^{N} \backslash D_{N}, 0\right)+\sum_{I=0}^{N-1}\binom{N}{I} \operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Theta_{\delta, \delta^{\prime}, I}^{*}, 0\right) \tag{3.26}
\end{align*}
$$

Lemma 3.5. Up to choosing $\delta^{\prime}$ sufficiently small in Lemma 3.2 (and $\tilde{\delta}$ and $\delta^{\prime \prime}$ correspondingly), we have that

$$
\begin{aligned}
\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Theta_{\delta, \delta^{\prime}, I}^{*}, 0\right)=\operatorname{deg}\left(\nabla_{X^{\prime}}\right. & \left.\Phi_{I},\left(\Omega_{\delta}\right)^{I} \backslash D_{I}, 0\right) \\
& \times \operatorname{deg}\left(\nabla_{X^{\prime \prime}} \tilde{\Phi}_{N-I},\left(\Sigma_{\delta^{\prime}}\right)^{N-I} \backslash D_{N-I}, 0\right)
\end{aligned}
$$

for $0 \leq I \leq N-1$, where

$$
X^{\prime}=\left(x_{1}, \ldots, x_{I}\right), \quad X^{\prime \prime}=\left(x_{I+1}, \ldots, x_{N}\right), \quad X=\left(X^{\prime}, X^{\prime \prime}\right)
$$

and the degrees are well-defined intersecting the domains with $\left(\Omega^{I} \backslash D_{I}\right)_{\delta^{\prime \prime}}$ and $\left(\Omega^{N-I} \backslash D_{N-I}\right)_{\delta^{\prime \prime}}$.

Proof. For $X \in \Theta_{\delta, \delta^{\prime}, I}^{*}$ we have

$$
\begin{equation*}
x_{i} \in \Omega_{\delta} \quad \text { for } 1 \leq i \leq I, \quad x_{a} \in \Sigma_{\delta^{\prime}} \quad \text { for } I+1 \leq a \leq N \tag{3.27}
\end{equation*}
$$

Interestingly, the gradient almost decouples into the first $I$ components and the last $N-I$. In fact, since $\tilde{\mathcal{H}}(x)$ coincides with $\mathcal{H}(x, x)$ for $x \in \Omega_{\delta}$, we have

$$
\tilde{\Phi}_{N}(X)=\Phi_{I}\left(X^{\prime}\right)+\tilde{\Phi}_{N-I}\left(X^{\prime \prime}\right)+\Xi_{I, N}(X)
$$

where

$$
\begin{aligned}
\tilde{\Phi}_{N-I}\left(X^{\prime \prime}\right) & =8 \pi \sum_{\substack{I+1 \leq a, b \leq N \\
a \neq b}} \mathcal{G}\left(x_{a}, x_{b}\right)+4 \pi \sum_{I+1 \leq a \leq N} \tilde{\mathcal{H}}\left(x_{a}\right) ; \\
\Xi_{I, N}(X) & =16 \pi \sum_{1 \leq i \leq I<a \leq N} \mathcal{G}\left(x_{i}, x_{a}\right)
\end{aligned}
$$

Notice that

$$
\mathcal{G}\left(x_{i}, x_{a}\right)=o_{\delta^{\prime}}(1), \quad \nabla \mathcal{G}\left(x_{i}, x_{a}\right)=o_{\delta^{\prime}}(1)
$$

with $o_{\delta^{\prime}}(1) \rightarrow 0$ as $\delta^{\prime} \rightarrow 0$ (for $\delta$ fixed), uniformly with respect to $x_{i}$ and $x_{a}$ as in (3.27). Now observe that $X=\left(x_{1}, \ldots, x_{N}\right) \in \partial \Theta_{\delta, \delta^{\prime}, \delta^{\prime \prime}, I}^{*}$ (with $\delta^{\prime \prime}<\frac{\tilde{\delta}}{2}$ to be fixed) implies that one of the following holds
(1) $\left|x_{i}-x_{j}\right|=\delta^{\prime \prime}$ for some $1 \leq i<j \leq I$;
(2) $\left|x_{a}-x_{b}\right|=\delta^{\prime \prime}$ for some $I+1 \leq a<b \leq N$;
(3) $d\left(x_{i}, \partial \Omega\right)=\delta$ for some $1 \leq i \leq I$;
(4) $d\left(x_{a}, \partial \Omega\right)=\delta^{\prime}$ for some $I+1 \leq a \leq N$;
(5) $d\left(x_{a}, \partial \Omega\right)=\delta^{\prime \prime}$ for some $I+1 \leq a \leq N$.

If we choose $M=M^{\prime}=M^{\prime \prime}=1$ in Lemmata $3.1,3.2$ and 3.3 and $\delta, \delta^{\prime}, \delta^{\prime \prime}$ sufficiently small, we obtain that in all the above cases

$$
\begin{equation*}
\max \left\{\left|\nabla_{X^{\prime}} \Phi_{I}\left(X^{\prime}\right)\right|,\left|\nabla_{X^{\prime \prime}} \tilde{\Phi}_{N-I}\left(X^{\prime \prime}\right)\right|\right\} \geq 1, \quad \text { for } X \in \partial \Theta_{\delta, \delta^{\prime}, \delta^{\prime \prime}, I}^{*} \tag{3.28}
\end{equation*}
$$

Then, by the analog of (3.23), we can choose $\delta^{\prime}$ even smaller (changing also $\tilde{\delta}$ accordingly) so that in addition to (3.28) we also have

$$
\begin{equation*}
\left|\nabla \Xi_{I, N}(X)\right| \leq \frac{1}{2} \quad \text { for } X \in \partial \Theta_{\delta, \delta^{\prime}, \delta^{\prime \prime}, I^{\prime}}^{*} \tag{3.29}
\end{equation*}
$$

Consider now for $t \in[0,1]$

$$
\tilde{\Phi}_{N}^{t}(X):=\Phi_{I}\left(X^{\prime}\right)+\tilde{\Phi}_{N-I}\left(X^{\prime \prime}\right)+t \Xi_{I, N}(X)
$$

Then (3.28)-(3.29) imply at once
$\left|\nabla \tilde{\Phi}_{N}^{t}(X)\right| \geq\left|\left(\nabla_{X^{\prime}} \Phi_{I}\left(X^{\prime}\right), \nabla_{X^{\prime \prime}} \tilde{\Phi}_{N-I}\left(X^{\prime \prime}\right)\right)\right|-\left|\nabla \Xi_{I, N}(X)\right|>0$ for $X \in \partial \Theta_{\delta, \delta^{\prime}, \delta^{\prime \prime}, I}^{*}$.
By the invariance of the degree under homotopy, we obtain

$$
\begin{align*}
\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Theta_{\delta, \delta^{\prime}, \delta^{\prime \prime}, I}^{*}, 0\right) & =\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}^{0}, \Theta_{\delta, \delta^{\prime}, \delta^{\prime \prime}, I}^{*}, 0\right) \\
& =\operatorname{deg}\left(\left(\nabla_{X^{\prime}} \Phi_{I}\left(X^{\prime}\right), \nabla_{X^{\prime \prime}} \tilde{\Phi}_{N-I}\left(X^{\prime \prime}\right)\right), \Theta_{\delta, \delta^{\prime}, \delta^{\prime \prime}, I}^{*}, 0\right) \tag{3.30}
\end{align*}
$$

and we conclude by the product formula of the degree.
Lemma 3.6. Up to choosing $\delta^{\prime}$ sufficiently small (reducing $\tilde{\delta}, \delta^{\prime \prime}$ accordingly), for $1 \leq J \leq N$ we have

$$
\operatorname{deg}\left(\nabla \tilde{\Phi}_{J},\left(\Sigma_{\delta^{\prime}}\right)^{J} \backslash D_{J}, 0\right)=0
$$



Proof. We will work on the the larger domain $\Sigma_{2 \delta^{\prime}}$, and modify $\tilde{\mathcal{H}}$ in the strip $\Sigma_{2 \delta^{\prime}} \backslash \Sigma_{\delta^{\prime}}=\bar{\Omega}_{\delta^{\prime}} \backslash \bar{\Omega}_{2 \delta^{\prime}}$ by defining

$$
\hat{\mathcal{H}}(x):=\tilde{\mathcal{H}}(x)+\sigma\left(\frac{d(x, \partial \Omega)}{\delta^{\prime}}\right)
$$

where $\sigma \in C^{\infty}([0,2))$ is non-negative, non-decreasing, and

$$
\sigma(t)= \begin{cases}0 & \text { for } 0 \leq t \leq 1 \\ \ln \left(\frac{1}{2-t}\right) & \text { for } \frac{3}{2} \leq t<2\end{cases}
$$

Clearly $\hat{\mathcal{H}}=\tilde{\mathcal{H}}$ in $\Sigma_{\delta^{\prime}}$, so that

$$
\begin{equation*}
\operatorname{deg}\left(\nabla \tilde{\Phi}_{J},\left(\Sigma_{\delta^{\prime}}\right)^{J} \backslash D_{J}, 0\right)=\operatorname{deg}\left(\nabla \hat{\Phi}_{J},\left(\Sigma_{\delta^{\prime}}\right)^{J} \backslash D_{J}, 0\right) \tag{3.31}
\end{equation*}
$$

where, for $\left(x_{1}, \ldots, x_{J}\right) \in\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash D_{J}$,

$$
\begin{align*}
\hat{\Phi}_{J}\left(x_{1}, \ldots, x_{J}\right) & =\tilde{\Phi}_{J}\left(x_{1}, \ldots, x_{J}\right)+\sum_{1 \leq i \leq J} \sigma\left(\frac{d\left(x_{i}, \partial \Omega\right)}{\delta^{\prime}}\right) \\
& =8 \pi \sum_{\substack{1 \leq i, j \leq J \\
i \neq j}} \mathcal{G}\left(x_{i}, x_{j}\right)+4 \pi \sum_{1 \leq i \leq J} \hat{\mathcal{H}}\left(x_{i}\right) \tag{3.32}
\end{align*}
$$

Thanks to Lemmata 3.7 and 3.8 below, we can choose $\delta^{\prime}>0$ even smaller than before, and $\tilde{\delta}$ accordingly small (without affecting the previous results, which are valid for $\delta^{\prime}, \tilde{\delta}$ and $\delta^{\prime \prime}$ sufficiently small), so that $\hat{\Phi}_{J}$ has no critical points in $\left(\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash\left(\Sigma_{\delta^{\prime}}\right)^{J}\right) \backslash D_{J}$. Then

$$
\begin{equation*}
\operatorname{deg}\left(\nabla \hat{\Phi}_{J},\left(\Sigma_{\delta^{\prime}}\right)^{J} \backslash D_{J}, 0\right)=\operatorname{deg}\left(\nabla \hat{\Phi}_{J},\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash D_{J}, 0\right) \tag{3.33}
\end{equation*}
$$

Since now

$$
\lim _{\left(x_{1}, \ldots, x_{J}\right) \rightarrow \partial\left(\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash D_{J}\right)} \hat{\Phi}_{J}\left(x_{1}, \ldots, x_{J}\right)=+\infty
$$

we can apply Proposition 3.1, and get

$$
\begin{equation*}
\operatorname{deg}\left(\nabla \hat{\Phi}_{J},\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash D_{J}, 0\right)=\chi\left(\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash D_{J}\right) \tag{3.34}
\end{equation*}
$$

On the other hand, $\chi\left(\Sigma_{2 \delta^{\prime}}\right)=0$, since $\Sigma_{2 \delta^{\prime}}$ retracts to a union of circles (up to choosing $\delta^{\prime}$ sufficiently small) and $\chi\left(\mathbb{S}^{1}\right)=0$. Then it follows from Proposition B. 1

$$
\chi\left(\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash D_{J}\right)=0
$$

This, together with (3.31), (3.33) and (3.34) yields $\operatorname{deg}\left(\nabla \tilde{\Phi}_{J},\left(\Sigma_{\delta^{\prime}}\right)^{J} \backslash D_{J}, 0\right)=$ $\chi\left(\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash D_{J}\right)=0$.

Lemma 3.7. For $1 \leq J \leq N$ and $M^{\prime}>0$ and $\delta>0$ there exists $\delta^{\prime} \in(0, \delta / 2)$ such that

$$
\left|\nabla \Psi_{J}\right| \geq M^{\prime} \quad \text { in }\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash D_{J}
$$

where, for $x_{1}, \ldots, x_{J} \in\left(\Omega \backslash \bar{\Omega}_{2 \delta^{\prime}}\right)^{J} \backslash D_{J}$,

$$
\begin{align*}
\Psi_{J}\left(x_{1}, \ldots, x_{J}\right) & :=\Phi_{J}\left(x_{1}, \ldots, x_{J}\right)+\sum_{1 \leq i \leq J} \sigma\left(\frac{d\left(x_{i}, \partial \Omega\right)}{\delta^{\prime}}\right) \\
& =8 \pi \sum_{\substack{1 \leq i, j \leq J \\
i \neq j}} \mathcal{G}\left(x_{i}, x_{j}\right)+4 \pi \sum_{1 \leq i \leq J} \mathcal{H}\left(x_{i}\right)+\sum_{1 \leq i \leq J} \sigma\left(\frac{d\left(x_{i}, \partial \Omega\right)}{\delta^{\prime}}\right), \tag{3.35}
\end{align*}
$$

and $\mathcal{G}$ and $\mathcal{H}$ are still the Green's function of $\Delta$ in $\Omega$ (not in $\Omega \backslash \bar{\Omega}_{2 \delta^{\prime}}$ ) and its regular part.

Proof. We assume by contradiction that there exist sequences $\delta_{k}^{\prime} \rightarrow 0^{+}$and

$$
\left(x_{1, k}, \ldots, x_{J, k}\right) \in\left(\Sigma_{2 \delta_{k}^{\prime}}\right)^{J} \backslash D_{J}
$$

such that

$$
\begin{equation*}
\nabla \Psi_{J}^{k}\left(x_{1, k}, \ldots, x_{J, k}\right)=O(1) \quad \text { as } k \rightarrow \infty \tag{3.36}
\end{equation*}
$$

where the notation $\Psi_{J}^{k}$ is meant to emphasize that $\Psi_{J}$ depends on $\delta_{k}^{\prime}$, due to the last term in (3.35). We proceed as in the proof of Lemma 3.1. Set

$$
r_{i, k}=\min \left\{d_{i, k}, \hat{d}_{i, k}, \min _{j \neq i}\left|x_{i, k}-x_{j, k}\right|\right\},
$$

where

$$
d_{i, k}:=d\left(x_{i, k}, \partial \Omega\right), \quad \hat{d}_{i, k}:=d\left(x_{i, k}, \partial \Omega_{2 \delta_{k}^{\prime}}\right)=2 \delta_{k}^{\prime}-d\left(x_{i, k}, \partial \Omega\right)
$$

Up to reordering we assume $r_{1, k} \leq r_{i, k}$ for every $1 \leq i \leq J$, and set

$$
r_{k}:=r_{1, k}, \quad d_{k}:=d_{1, k}, \quad \hat{d}_{k}:=\hat{d}_{1, k}, \quad x_{k}:=x_{1, k}
$$

Define $\mathcal{D}, Z_{k}, Z_{k}^{\prime} \rightarrow Z_{\infty}^{\prime}, \Omega_{k}$, as in the proof of Lemma 3.1, and similarly

$$
\left(\Sigma_{2 \delta_{k}^{\prime}}\right)_{k}:=r_{k}^{-1}\left(\Sigma_{2 \delta_{k}^{\prime}}-x_{k}\right)
$$

Then we set, for $Z=\left(z_{1}, \ldots, z_{J}\right) \in\left(\left(\Sigma_{2 \delta_{k}^{\prime}}\right)_{k}\right)^{J} \backslash D_{J}$,

$$
\begin{align*}
\hat{\Xi}_{\mathcal{D}, k}\left(z_{1}, \ldots, z_{N}\right):= & 8 \pi \sum_{\substack{i, j \in \mathcal{D} \\
i \neq j}} \mathcal{G}_{k}\left(z_{i}, z_{j}\right)+16 \pi \sum_{i \in \mathcal{D}} \sum_{\substack{1 \leq j \leq N \\
j \notin \mathcal{D}}} \mathcal{G}_{k}\left(z_{i}, z_{j}\right)  \tag{3.37}\\
& +4 \pi \sum_{i \in \mathcal{D}} \mathcal{H}_{k}\left(z_{i}, z_{i}\right)+\sum_{i \in \mathcal{D}} \sigma\left(\frac{r_{k} d\left(z_{i}, \partial \Omega_{k}\right)}{\delta_{k}^{\prime}}\right)
\end{align*}
$$

where $\mathcal{G}_{k}$ and $\mathcal{H}_{k}$ are the Green's function of $\Delta$ on $\Omega_{k}$ and its regular part, respectively. Observe that $r_{k} \leq \delta_{k}^{\prime} \rightarrow 0$ as $k \rightarrow \infty$. We consider several cases.
Case 1 Assume that, up to a subsequence, $r_{k}=o\left(d_{k}\right), r_{k}=o\left(\hat{d}_{k}\right)$ as $k \rightarrow \infty$. Since

$$
\nabla_{z} \sigma\left(\frac{r_{k} d\left(z, \partial \Omega_{k}\right)}{\delta_{k}^{\prime}}\right)=\nabla_{z} \sigma\left(\frac{d\left(x_{k}+r_{k} z, \partial \Omega\right)}{\delta_{k}^{\prime}}\right)=\left.r_{k} \nabla_{x} \sigma\left(\frac{d(x, \partial \Omega)}{\delta_{k}^{\prime}}\right)\right|_{x=x_{k}+r_{k} z}
$$

and

$$
\sigma^{\prime}\left(\frac{d\left(x_{i, k}, \partial \Omega\right)}{\delta_{k}^{\prime}}\right)=O\left(\frac{\delta_{k}^{\prime}}{\hat{d}_{k}}\right), \quad|\nabla d(\cdot, \partial \Omega)|=1, \quad \text { for } i \in \mathcal{D}
$$

we infer

$$
\nabla_{z} \sigma\left(\frac{r_{k} d\left(z_{i, k}, \partial \Omega_{k}\right)}{\delta_{k}^{\prime}}\right)=O\left(\frac{r_{k}}{\hat{d}_{k}}\right)=o(1) \quad \text { as } k \rightarrow \infty, \quad \text { for } i \in \mathcal{D}
$$

Then we can proceed as in Case 1 of the proof of Lemma 3.1 to get that $Z_{\infty}^{\prime}$ is critical point of $\Xi_{\mathcal{D}, \mathbb{R}^{2}}$, as defined in (3.15), contradicting Lemma A.3.
Case 2 Assume that, up to a subsequence, $r_{k}=o\left(\hat{d}_{k}\right), \frac{d_{k}}{r_{k}} \rightarrow L \geq 1$ as $k \rightarrow \infty$. This implies that $r_{k}=o\left(\delta_{k}^{\prime}\right)$ as $k \rightarrow \infty$ and, up to a rotation, $\left(\Sigma_{\delta_{k}^{\prime}}\right)_{k}$ converges to a half-space $H=\left\{(x, y) \in \mathbb{R}^{2}: y<L\right\}$. We proceed as in Case 1, except that now

$$
\sigma\left(\frac{r_{k} d\left(z_{i, k}, \partial \Omega_{k}\right)}{\delta_{k}^{\prime}}\right)=0, \quad \text { for } i \in \mathcal{D}, \quad k \text { large enough. }
$$

Then $\hat{\Xi}_{\mathcal{D}, k}\left(Z_{k}\right)=\Xi_{\mathcal{D}, k}\left(Z_{k}\right)$ for $k$ large enough, where $\Xi_{\mathcal{D}, k}$ is as in (3.11) (with $t_{k}=0$ ). Then we are in the same situation as Case 2 of the proof of Lemma 3.1, leading to the same contradiction, i.e. $Z_{\infty}^{\prime}$ is a critical point of $\Xi_{\mathcal{D}, H}$, violating Lemma A. 5 .
Case 3 Assume that, up to a subsequence, $r_{k}=o\left(d_{k}\right), \frac{\hat{d}_{k}}{r_{k}} \rightarrow \hat{L}_{1} \geq 1$. This implies in particular that, up to a subsequence,

$$
\begin{equation*}
r_{k}=o\left(\delta_{k}^{\prime}\right), \quad \frac{\hat{d}_{i, k}}{r_{k}} \rightarrow \hat{L}_{i} \geq 1 \quad \text { as } k \rightarrow \infty, \text { for } i \in \mathcal{D} \tag{3.38}
\end{equation*}
$$

Then, up to a rotation $\left(\Sigma_{2 \delta_{k}^{\prime}}\right)_{k}$ converges to $\hat{H}=\left\{(x, y) \in \mathbb{R}^{2}: y>-\hat{L}\right\}$. As before, $r_{k}=o\left(d_{k}\right)$ implies $r_{k}=o\left(d_{i, k}\right)$ for $i \in \mathcal{D}$ and it follows $\nabla \mathcal{H}_{k}\left(z_{i, k}, z_{i, k}\right)=O\left(r_{k}\right)$ as $k \rightarrow \infty$ for $i \in \mathcal{D}$. Considering that

$$
\frac{r_{k} d\left(z_{i, k}, \partial \Omega_{k}\right)}{\delta_{k}^{\prime}}=\frac{d\left(x_{i, k}, \partial \Omega\right)}{\delta_{k}^{\prime}} \rightarrow 2, \quad \text { as } k \rightarrow \infty, \quad \text { for } i \in \mathcal{D}
$$

and $\sigma(t)=-\ln (2-t)$ for $\frac{3}{2} \leq t<2$, we have that

$$
\begin{align*}
\nabla_{z} \sigma\left(\frac{r_{k} d\left(z_{i, k}, \partial \Omega_{k}\right)}{\delta_{k}^{\prime}}\right) & =\frac{r_{k} \nabla d\left(z_{i, k}, \partial \Omega_{k}\right)}{2 \delta_{k}^{\prime}-r_{k} d\left(z_{i, k}, \partial \Omega_{k}\right)}=\frac{-r_{k} \nabla d\left(z_{i, k}, \partial\left(\Omega \backslash \Omega_{2 \delta_{k}^{\prime}}\right)_{k}\right)}{\hat{d}_{i, k}} \\
& \rightarrow-\frac{\nabla_{z} d\left(z_{i, \infty}, \partial \hat{H}\right)}{\hat{L}_{i}}=\nabla_{z} \ln \frac{1}{d\left(z_{i, \infty}, \partial \hat{H}\right)} \tag{3.39}
\end{align*}
$$

since $\hat{L}_{i}=d\left(z_{i, \infty}, \partial \hat{H}\right)$. Then $Z_{\infty}^{\prime}$ is a critical point of

$$
\hat{\Xi}_{\mathcal{D}, \hat{H}}(Z)=4 \sum_{\substack{i, j \in \mathcal{D} \\ i \neq j}} \ln \frac{1}{\left|z_{i}-z_{j}\right|}+\sum_{i \in \mathcal{D}} \ln \frac{1}{d\left(z_{i}, \partial \hat{H}\right)}
$$

contradicting Lemma A.4.
Case 4 If we are not in any of the above cases, then, up to a subsequence,

$$
\frac{d_{k}}{r_{k}} \rightarrow L_{1} \geq 1, \quad \frac{\hat{d}_{k}}{r_{k}} \rightarrow \hat{L}_{1} \geq 1, \quad \text { as } k \rightarrow \infty
$$

Then,

$$
\frac{r_{k}}{\delta_{k}^{\prime}} \rightarrow \gamma>0, \quad \text { as } k \rightarrow \infty
$$

and,

$$
\frac{d_{i, k}}{r_{k}} \rightarrow L_{i} \geq 1, \quad \frac{\hat{d}_{i, k}}{r_{k}} \rightarrow \hat{L}_{i} \geq 1, \quad \frac{\hat{d}_{i, k}}{\delta_{k}^{\prime}} \rightarrow \rho_{i} \in(0,2), \quad \text { as } k \rightarrow \infty, \quad i \in \mathcal{D} .
$$

Up to a rotation $\left(\Sigma_{2 \delta_{k}^{\prime}}\right)_{k}$ converges to $H \cap \hat{H}$, where

$$
H=\left\{(x, y) \in \mathbb{R}^{2}: y<L_{1}\right\}, \quad \hat{H}=\left\{(x, y) \in \mathbb{R}^{2}: y>-\hat{L}_{1}\right\}
$$

Considering now that

$$
L_{i}+o(1)=\frac{d_{i, k}}{r_{k}}=d\left(z_{i, k}, \partial \Omega_{k}\right)=d\left(z_{i, \infty}, \partial H\right)+o(1), \quad \text { as } k \rightarrow \infty, \quad \text { for } i \in \mathcal{D}
$$

we compute

$$
\begin{aligned}
\nabla_{z} \sigma\left(\frac{r_{k} d\left(z_{i, k}, \partial \Omega_{k}\right)}{\delta_{k}^{\prime}}\right) & =\frac{r_{k}}{\delta_{k}^{\prime}} \sigma^{\prime}\left(\frac{d_{i, k}}{\delta_{k}^{\prime}}\right) \nabla_{z} d\left(z_{i, k}, \partial \Omega_{k}\right) \\
& \rightarrow \gamma \sigma^{\prime}\left(\gamma L_{i}\right) \nabla_{z} d\left(z_{i, \infty}, \partial H\right) \\
& =\nabla_{z} \sigma\left(\gamma d\left(z_{i, \infty}, \partial H\right)\right), \quad \text { as } k \rightarrow \infty, \quad \text { for } i \in \mathcal{D}
\end{aligned}
$$

Then $Z_{\infty}^{\prime}$ is a critical point of

$$
\hat{\Xi}_{\mathcal{D}, \hat{H}}\left(Z^{\prime}\right)=8 \pi \sum_{\substack{i, j \in \mathcal{D} \\ i \neq j}} \mathcal{G}_{H}\left(z_{i}, z_{j}\right)+4 \pi \sum_{i \in \mathcal{D}} \mathcal{H}_{H}\left(z_{i}\right)+\sum_{i \in \mathcal{D}} \sigma\left(\gamma d\left(z_{i}, H\right)\right)
$$

This contradicts Lemma A.6.
These contradictions, arising from (3.36), complete the proof of the lemma.
$\underset{\sim}{\text { Lemma 3.8. Given }} 1 \leq J \leq N$ and $\delta^{\prime}$ as in Lemma 3.7 (or smaller), there exists $\tilde{\delta} \in\left(0, \frac{\delta^{\prime}}{2}\right)$ sufficiently small such that $\hat{\Phi}_{J}$ (defined as in (3.32), hence depending on $\tilde{\delta})$ has no critical points in $\left(\left(\Sigma_{2 \delta^{\prime}}\right)^{J} \backslash\left(\Sigma_{\delta^{\prime}}\right)^{J}\right) \backslash D_{J}$.

Proof. This follows as in the proof of Lemma 3.2 by a contradiction argument, using Lemma 3.7 instead of Lemma 3.1. Here $2 \delta^{\prime}$ plays the role of $\delta$ in Lemma 3.7.
3.4. Proof of Proposition 2.4 (completed). By Corollary 2.3 we can assume $h \equiv 1$ and work with $\Phi_{N}$ instead of $\Phi_{N, h}$. Using Lemma 3.1, considering that $\Phi_{N}$ coincides with $\tilde{\Phi}_{N}$ on $\left(\Omega_{\delta}\right)^{N} \backslash D_{N}$, using formula (3.26) and Lemmata 3.5 and 3.6 we now get

$$
\begin{aligned}
\operatorname{deg}\left(\nabla \Phi_{N}, \Omega^{N} \backslash D_{N}, 0\right) & =\operatorname{deg}\left(\nabla \Phi_{N},\left(\Omega_{\delta}\right)^{N} \backslash D_{N}, 0\right) \\
& =\operatorname{deg}\left(\nabla \tilde{\Phi}_{N},\left(\Omega_{\delta}\right)^{N} \backslash D_{N}, 0\right) \\
& =\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Omega^{N} \backslash D_{N}, 0\right)-\sum_{0 \leq I \leq N-1} \operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Theta_{\delta, \delta^{\prime}, I}, 0\right) \\
& =\operatorname{deg}\left(\nabla \tilde{\Phi}_{N}, \Omega^{N} \backslash D_{N}, 0\right)
\end{aligned}
$$

By Lemma 3.4 we finally obtain

$$
\operatorname{deg}\left(\nabla \Phi_{N}, \Omega^{N} \backslash D_{N}, 0\right)=\chi(\Omega)(\chi(\Omega)-1) \ldots(\chi(\Omega)-N+1)
$$

## Appendix A. Properties of the Green's function

For some fixed $L, \hat{L}>0$, let $H$ and $\hat{H}$ denote the half spaces

$$
\begin{equation*}
H=\left\{(x, y) \in \mathbb{R}^{2}: y<L\right\}, \quad \hat{H}=\left\{(x, y) \in \mathbb{R}^{2}: y>-\hat{L}\right\} \tag{A.1}
\end{equation*}
$$

On the half-space $H$, the Green's function and its regular part are given explicitly by

$$
\begin{equation*}
\mathcal{G}_{H}(z, \eta)=\frac{1}{2 \pi} \ln \frac{\left|z-\eta^{*}\right|}{|z-\eta|}, \quad \mathcal{H}_{H}(z, \eta)=\frac{1}{2 \pi} \ln \left|z-\eta^{*}\right| \tag{A.2}
\end{equation*}
$$

where $\eta^{*}$ is the reflection of $\eta$ across $\partial H$.
Consider now $\Omega \subset \mathbb{R}^{2}$ smoothly bounded. For $x_{k} \in \Omega, d_{k}:=d\left(x_{k}, \partial \Omega\right), r_{k}>0$, let $\mathcal{G}_{k}(z, \eta)$ and $\mathcal{H}_{k}(z, \eta)$ denote the Green's function of $\Delta$ in $\Omega_{k}:=r_{k}^{-1}\left(\Omega-x_{k}\right)$ and its regular part.

Lemma A.1. With the above notation, assume that, up to a subsequence, $r_{k}=$ $o\left(d_{k}\right)$, so that $\Omega_{k}$ invades $\mathbb{R}^{2}$ as $k \rightarrow \infty$. Then, for every compact set $K \subset \mathbb{R}^{2}$, there exists $C_{K}$ such that

$$
\left|\nabla_{z}\left(\mathcal{G}_{k}(z, \eta)-\frac{1}{2 \pi} \ln \frac{1}{|z-\eta|}\right)\right| \leq C_{K} \frac{r_{k}}{d_{k}}
$$

and

$$
\left|\nabla_{z} \mathcal{H}_{k}(z, z)\right| \leq C_{K} \frac{r_{k}}{d_{k}}
$$

uniformly for $z \in K, \eta \in \Omega_{k}$.
Proof. This follows from Appendix B in [19].
Lemma A.2. With the above notation, assume that, up to a subsequence and a rotation, $r_{k} \rightarrow 0, d_{k} / r_{k} \rightarrow L \in(0, \infty)$, and $\Omega_{k}$ converges to the half-space $H$ as $k \rightarrow \infty$. Then for every compact set $K \subset H$ and for $k$ large enough

$$
\left\|\nabla\left(\mathcal{H}_{k}-\mathcal{H}_{H}\right)\right\|_{L^{\infty}\left(K \times \Omega_{k, \rho}\right)} \leq C_{K} r_{k} \max \left\{1, \rho^{-1}\right\}
$$

and

$$
\left\|\nabla\left(\mathcal{G}_{k}-\mathcal{G}_{H}\right)\right\|_{L^{\infty}\left(K \times \Omega_{k, \rho}\right)} \leq C_{K} r_{k} \max \left\{1, \rho^{-1}\right\}
$$

where $\Omega_{k, \rho}:=\left\{z \in \Omega_{k}: d\left(z, \partial \Omega_{k}\right)>\rho\right\}$.
Proof. We have

$$
\begin{cases}\Delta_{z} \mathcal{H}_{k}(z, \eta)=0 & \text { in } \Omega_{k} \times \Omega_{k}  \tag{A.3}\\ \mathcal{H}_{k}(z, \eta)=\frac{1}{2 \pi} \ln |z-\eta| & \text { for } z \in \partial \Omega_{k}, y \in \Omega_{k}\end{cases}
$$

We apply the maximum principle to the function

$$
\mathcal{H}_{k}(z, \cdot)-\mathcal{H}_{H}(z, \cdot): \Omega_{k} \rightarrow \mathbb{R}
$$

where $z \in K$ and $K \subset H$ is a fixed compact set. We want to prove that

$$
\begin{equation*}
\sup _{z \in K, \eta \in \partial \Omega_{k}}\left|\mathcal{H}_{k}(z, \eta)-\mathcal{H}_{H}(z, \eta)\right| \leq C(K) r_{k} \tag{A.4}
\end{equation*}
$$

for $k$ sufficiently large. By definition we have

$$
\mathcal{H}_{k}(z, \eta)=\frac{1}{2 \pi} \ln |z-\eta|, \quad \mathcal{H}_{H}(z, \eta)=\frac{1}{2 \pi} \ln \left|z-\eta^{*}\right| \quad \text { for } \eta \in \partial \Omega_{k}
$$

Let $\delta>0$ be so small that $\partial \Omega \cap B_{\delta}\left(p\left(x_{k}\right)\right)$ can be written as the graph over $[-\delta, \delta]$ of a function $f$, where $p\left(x_{k}\right)$ is the nearest point projection of $x_{k}$ onto $\partial \Omega$. Let
$\mathcal{L} \subset \mathbb{R}^{2}$ be the tangent line to $\partial \Omega$ at $p\left(x_{k}\right)$ and $f: \mathcal{L} \cap B_{\delta}\left(x_{k}\right) \rightarrow \mathbb{R}$. Up to a rotation we can assume that $f^{\prime}\left(p\left(x_{k}\right)\right)=0$ and by a Taylor expansion we obtain

$$
|f(t)| \leq \frac{\sup _{[-\delta, \delta]} f^{\prime \prime}}{2} t^{2}, \quad t \in[-\delta, \delta]
$$

In particular for each $x \in \partial \Omega \cap B_{\delta}\left(x_{k}\right)$ we have $d(x, L) \leq C_{\Omega, \delta}\left|x-x_{k}\right|^{2}$. Scaling to $\Omega_{k}$ we then obtain

$$
\eta \in \partial \Omega_{k}, \quad|\eta| \leq \frac{\delta}{r_{k}} \quad \Rightarrow \quad d(\eta, \partial H)=O\left(r_{k}\right)
$$

Then, for such $\eta$ and for $z \in K$, we have $|z-\eta| \leq\left|z-\eta^{*}\right|+O\left(r_{k}\right)$ and

$$
\left|\mathcal{H}_{k}-\mathcal{H}_{H}\right|=\left|\ln \frac{|z-\eta|}{\left|z-\eta^{*}\right|}\right| \leq \ln \left(1+\frac{O\left(r_{k}\right)}{\left|z-\eta^{*}\right|}\right)=C(K) O\left(r_{k}\right)
$$

since $\frac{1}{\left|z-\eta^{*}\right|} \geq \varepsilon(K)>0$ uniformly for $z \in K$. On the other hand

$$
\eta \in \partial \Omega_{k}, \quad|\eta| \geq \frac{\delta}{r_{k}} \quad \Rightarrow \quad\left|z-\eta^{*}\right|-|z-\eta| \leq C(K)
$$

Then

$$
\left|\mathcal{H}_{k}-\mathcal{H}_{H}\right|=\left|\ln \frac{|z-\eta|}{\left|z-\eta^{*}\right|}\right| \leq \ln \left(1+\frac{r_{k} C(K)}{\delta}\right)=C(K) O\left(r_{k}\right)
$$

so that (A.4) is proven. By the maximum principle we obtain

$$
\begin{equation*}
\sup _{z \in K, \eta \in \Omega_{k}}\left|\mathcal{H}_{k}(z, \eta)-\mathcal{H}_{H}(z, \eta)\right|=C(K) O\left(r_{k}\right), \tag{A.5}
\end{equation*}
$$

and the bound on $\nabla\left(\mathcal{H}_{k}-\mathcal{H}_{H}\right)$ follows by elliptic estimates, since both $\mathcal{H}_{H}(z, \cdot)$ and $\mathcal{H}_{k}(z, \cdot)$ are harmonic. The estimate of $\nabla\left(\mathcal{G}_{k}-\mathcal{G}_{H}\right)$ follows at once since $\mathcal{G}_{k}-\mathcal{G}_{H}=\mathcal{H}_{k}-\mathcal{H}_{H}$.

We state Lemmata A.3, A. 4 and A. 5 below with general positive coefficients $\alpha_{i, j}$ and $\beta_{i}$ for future reference, and also to remark that the coefficients $8 \pi$ and $4 \pi$ appearing in the definitions of $\Phi_{N, h}, \Phi_{N}$, etc..., can be replaced by any other positive constants.
Lemma A.3. Consider for some $J \geq 2$ the functional $\Xi_{J, \mathbb{R}^{2}}:\left(\mathbb{R}^{2}\right)^{J} \backslash D_{J} \rightarrow \mathbb{R}$

$$
\Xi_{J, \mathbb{R}^{2}}\left(z_{1}, \ldots, z_{J}\right):=\sum_{\substack{1 \leq i, j \leq J \\ i \neq j}} \alpha_{i, j} \ln \frac{1}{\left|z_{i}-z_{j}\right|}
$$

with $\alpha_{i, j}>0$ for $1 \leq i, j \leq J, i \neq j$. Then $\Xi_{J, \mathbb{R}^{2}}$ has no critical points.
Proof. Consider $1 \leq i \leq J$ such that $z_{i}$ lies on the boundary of the convex hull of $\left\{z_{1}, \ldots, z_{J}\right\}$, and observe that the derivative with respect to $z_{i}$ in a direction pointing outwards of the convex hull is negative, as $\left|z_{i}-z_{j}\right|$ is increasing for every $1 \leq i \neq j \leq J$.

Lemma A.4. Consider for some $J \geq 1$ the functional $\hat{\Xi}_{J, \hat{H}}: \hat{H}^{J} \backslash D_{J} \rightarrow \mathbb{R}$

$$
\hat{\Xi}_{J, \hat{H}}\left(z_{1}, \ldots, z_{J}\right):=\sum_{\substack{1 \leq i, j \leq J \\ i \neq j}} \alpha_{i, j} \ln \frac{1}{\left|z_{i}-z_{j}\right|}+\sum_{1 \leq i \leq J} \gamma_{i} \ln \frac{1}{d\left(z_{i}, \partial \hat{H}\right)}
$$

with $\alpha_{i, j}>0$ for $1 \leq i<j \leq J$ and $\gamma_{i}>0$ for $1 \leq i \leq J$. Then $\hat{\Xi}_{J, \hat{H}}$ has no critical point.

Proof. Given $\left(z_{1}, \ldots, z_{J}\right)$, write $z_{i}=\left(a_{i}, b_{i}\right)$ and up to reordering, assume that $b_{1} \leq \cdots \leq b_{J}$, i.e. $z_{J}$ is one of the points farthest from $\partial \hat{H}$. Then

$$
\frac{\partial}{\partial b_{J}} \ln \frac{1}{\left|z_{i}-z_{J}\right|} \leq 0, \quad \text { for } 1 \leq i<J, \quad \frac{\partial}{\partial b_{J}} \ln \frac{1}{d\left(z_{J}, \partial \hat{H}\right)}<0
$$

hence

$$
\frac{\partial \hat{\Xi}_{J, \hat{H}}\left(z_{1}, \ldots, z_{J}\right)}{\partial b_{J}}<0
$$

Lemma A.5. Consider for some $J \geq 1$ the functionals $\Xi_{J, H}^{ \pm}: H^{J} \backslash D_{J} \rightarrow \mathbb{R}$ given as

$$
\Xi_{J, H}^{ \pm}\left(z_{1}, \ldots, z_{J}\right):=\sum_{\substack{1 \leq i, j \leq J \\ i \neq j}} \alpha_{i, j} \mathcal{G}_{H}\left(z_{i}, z_{j}\right) \pm \sum_{1 \leq i \leq J} \beta_{j} \mathcal{H}_{H}\left(z_{i}, z_{i}\right)
$$

with $\alpha_{i, j}>0$ for $1 \leq i, j \leq J, i \neq j, \beta_{j}>0$ for $1 \leq i \leq J$. Then $\Xi_{J, H}^{ \pm}$has no critical points.

Proof. Given $\left(z_{1}, \ldots, z_{J}\right)$, write in coordinates $z_{i}=\left(a_{i}, b_{i}\right) \in H$ for $1 \leq i \leq J$ and, up to reordering, assume first that $J>1, a_{1} \leq a_{2} \leq \cdots \leq a_{J}$ and $a_{1}<a_{J}$. Then, it follows from (A.2)

$$
\frac{\partial \mathcal{G}_{H}\left(z_{1}, z_{J}\right)}{\partial a_{1}}>0, \quad \frac{\partial \mathcal{G}_{H}\left(z_{1}, z_{j}\right)}{\partial a_{1}} \geq 0, \text { for } 2 \leq j \leq J-1, \quad \frac{\partial \mathcal{H}_{H}\left(z_{1}, z_{1}\right)}{\partial a_{1}}=0
$$

hence $\nabla_{z_{1}} \Xi_{J, H}^{ \pm}\left(z_{1}, \ldots, z_{J}\right) \neq 0$.
If $J=1$ or all the $z_{i}^{\prime} s$ are vertically, i.e. $a_{1}=\cdots=a_{J}$, then, up to reordering, assume that $b_{1}<\cdots<b_{J}$. Then, again from (A.2), we get

$$
\begin{equation*}
\frac{\partial \mathcal{G}_{H}\left(z_{1}, z_{j}\right)}{\partial b_{1}}<0, \quad \text { for } 2 \leq j \leq J, \quad \frac{\partial \mathcal{H}_{H}\left(z_{1}, z_{1}\right)}{\partial b_{1}}<0 \tag{A.6}
\end{equation*}
$$

hence $\nabla_{z_{1}} \Xi_{J, H}^{+}\left(z_{1}, \ldots, z_{J}\right) \neq 0$, and

$$
\frac{\partial \mathcal{G}_{H}\left(z_{J}, z_{j}\right)}{\partial b_{J}}>0, \quad \text { for } 2 \leq j \leq J, \quad \frac{\partial \mathcal{H}_{H}\left(z_{J}, z_{J}\right)}{\partial b_{J}}<0
$$

hence $\nabla_{z_{N}} \Xi_{J, H}^{-}\left(z_{1}, \ldots, z_{J}\right) \neq 0$.
Lemma A.6. Consider for some $J \geq 1$ the functional $\Xi_{J, H, \hat{H}}^{\varphi}:(H \cap \hat{H})^{J} \backslash D_{J} \rightarrow \mathbb{R}$ given as

$$
\Xi_{J, H, \hat{H}}^{\varphi}\left(z_{1}, \ldots, z_{J}\right):=\Xi_{J, H}^{+}\left(z_{1}, \ldots, z_{J}\right)+\sum_{1 \leq i \leq J} \gamma_{i} \varphi\left(z_{i}\right),
$$

where $H$ and $\hat{H}$ are as in (A.1) for some $L, \hat{L}>0, \Xi_{J, H}^{+}$is as in Lemma A.5, $\gamma_{i} \geq 0$, for $1 \leq i \leq J, \varphi \in C^{1}(H \cap \hat{H})$ and $\nabla \varphi(z) \cdot(0,1) \leq 0$ for every $z \in H \cap \hat{H}$. Then $\Xi_{J, H, \hat{H}}^{\varphi}$ has no critical points.
Proof. The proof is identical to the proof of Lemma A.5, using (A.6) together with

$$
\frac{\partial \varphi\left(z_{1}\right)}{\partial b_{1}}=\nabla \varphi\left(z_{1}\right) \cdot(0,1) \leq 0
$$

## Appendix B. The Euler characteristic of configuration spaces

We will need the following general fact about configuration spaces.
Proposition B.1. Let $\Omega$ be a smoothly bounded domain of $\mathbb{R}^{2}$ and call for any $N \in \mathbb{N}^{\star}$

$$
F(\Omega, N):=\Omega^{N} \backslash D_{N}=\left\{\left(x_{1}, \ldots, x_{N}\right) \in \Omega^{N}: x_{i} \neq x_{j} \text { for } i \neq j\right\}
$$

Then

$$
\chi(F(\Omega, N))=\chi(\Omega)(\chi(\Omega)-1) \ldots(\chi(\Omega)-N+1) .
$$

Proof. This result follows from the fact that $F(\Omega, N)$ fibers on $F(\Omega, N-1)$ with fiber $\Omega_{N-1}$ (projecting on the last of the $N$ points), where we denote by $\Omega_{j}$ the set $\Omega$ with $j$ points removed, see [35, Chapter 2 ].

Claim The above fibration is orientable, in the sense that $\pi_{1}(F(\Omega, N-1))$ acts trivially on the homology $H_{*}\left(\Omega_{N-1}, \mathbb{R}\right)$ of the fiber.

Proof of the claim. Since $\Omega_{N-1}$ is homotopically equivalent to a (connected) finite union of circles, the only relevant homology group of $\Omega_{N-1}$ is $H_{1}\left(\Omega_{N-1}, \mathbb{R}\right)$. Consider now a closed path $\gamma \in C^{0}([0,1], F(\Omega, N-1))$ representing a homotopy class $[\gamma] \in \pi_{1}(F(\Omega, N-1))$. Set

$$
\left(x_{1}(t), \ldots, x_{N-1}(t)\right):=\gamma(t)
$$

For the point $\gamma(0)=:\left(x_{1}, \ldots, x_{N-1}\right) \in F(\Omega, N-1)$ consider the fiber

$$
\Omega \backslash\left\{x_{1}, \ldots, x_{N-1}\right\} \simeq \Omega_{N-1}
$$

and choose generators of its first homology group as follows. Since $\Omega$ is a twodimensional domain, it is homotopic to a disk with $r$ points removed, for $r=$ $0,1,2, \ldots$ Given the $i$-th hole of $\Omega, i=1, \ldots, r$, choose an element $\sigma_{i}$ of $H_{1}(\Omega, \mathbb{R})$ in the form of a smooth Jordan curve that does not contain any of the points $x_{1}(t), \ldots, x_{N-1}(t)$ with $t \in[0,1]$. Then it is clear that the action of $\gamma$ on $\sigma_{1}, \ldots, \sigma_{r}$ is trivial.

Now, for each $x_{j}, j=1, \ldots, k-1$, choose a small and smooth Jordan curve $\eta_{j}$ around $x_{j}$ not intersecting $\sigma_{1}, \ldots, \sigma_{r}$, for instance the oriented boundary of $B_{\varepsilon}\left(x_{j}\right)$. By compactness, if we choose $\varepsilon$ small enough we get

$$
\overline{B_{\varepsilon}\left(x_{j}(t)\right)} \cap \overline{B_{\varepsilon}\left(x_{i}(t)\right)}=\emptyset, \quad \text { for } 1 \leq i<j \leq N-1, t \in[0,1]
$$

and

$$
\overline{B_{\varepsilon}\left(x_{j}(t)\right)} \cap \sigma_{i}=\emptyset, \quad \text { for } 1 \leq j \leq N-1,1 \leq i \leq r, t \in[0,1] .
$$

Again it follows immediately that the action of $[\gamma]$ of $\eta_{j}$ is trivial. Since

$$
H_{1}\left(\Omega_{N-1}, \mathbb{R}\right)=\operatorname{span}\left\{\sigma_{i}, \eta_{j}, 1 \leq i \leq r, 1 \leq j \leq N-1\right\}
$$

the claim is proven.
By the product formula for orientable fibrations, see Spanier [35, p.481], we infer

$$
\chi(F(\Omega, N))=\chi(F(\Omega, N-1)) \chi\left(\Omega_{N-1}\right)=\chi(F(\Omega, N-1))(\chi(\Omega)-N+1) .
$$

Now the proposition follows at once by induction in $N$.

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